Joint Classifier and Feature Optimization for Comprehensive Cancer Diagnosis Using Gene Expression Data

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ABSTRACT

Recent research has demonstrated quite convincingly that accurate cancer diagnosis can be achieved by constructing classifiers that are designed to compare the gene expression profile of a tissue of unknown cancer status to a database of stored expression profiles from tissues of known cancer status. This paper introduces the JCFO, a novel algorithm that uses a sparse Bayesian approach to jointly identify both the optimal nonlinear classifier for diagnosis and the optimal set of genes on which to base that diagnosis. We show that the diagnostic classification accuracy of the proposed algorithm is superior to a number of current state-ofthe-art methods in a full leave-one-out cross-validation study of five widely used benchmark datasets. In addition to its superior classification accuracy, the algorithm is designed to automatically identify a small subset of genes (typically around twenty in our experiments) that are capable of providing complete discriminatory information for diagnosis. Focusing attention on a small subset of genes is useful not only because it produces a classifier with good generalization capacity, but also because this set of genes may provide insights into the mechanisms responsible for the disease itself. A number of the genes identified by the JCFO in our experiments are already in use as clinical markers for cancer diagnosis; some of the remaining genes may be excellent candidates for further clinical investigation. If it is possible to identify a small set of genes that is indeed capable of providing complete discrimination, inexpensive diagnostic assays might be widely deployable in clinical settings.

Key words: disease diagnosis, classification, feature selection, joint optimization, sparse Bayesian methods, JCFO, RVM, SVM.

1. INTRODUCTION

TN AN EFFORT TO IMPROVE THE ACCURACY OF CANCER DIAGNOSIS and enable the prediction of patient response to different treatment options, a considerable amount of research effort has recently been expended to develop methods that are capable of leveraging the availability of databases of gene expression profiles collected from various classes of cancers (Golub *et al.*, 1999). While a large number of supervised

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and unsupervised methods from the pattern recognition literature have been proposed in this context, techniques based on linear support vector machines (SVM) have proven to be the most popular, and also quite accurate (Ben-Dor *et al.*, 2000; Furey *et al.*, 2000; Guyon *et al.*, 2002).

Other recent research has shown that the expression levels of fewer than ten genes are often sufficient for accurate diagnosis of most cancers, even though the expression levels of a large number of genes are strongly correlated with the disease (Frank, 2002; Xiong *et al.*, 2001). In fact, the use of a much larger set of gene expression levels has been shown to have a deleterious effect on the diagnostic accuracy due to the phenomenon known as the *curse of dimensionality*, in which the risk of overfitting increases as the dimensionality of data grows relative to the number of training samples. By identifying a small subset of genes on which to base a diagnosis, we can not only achieve improved diagnostic accuracy, but also gain possibly significant insights into the nature of the disease and the genetic mechanisms responsible for it. In addition, assays that require very few gene expression levels to be measured in order to make a diagnosis are far more likely to be widely deployed in a clinical setting.

In this paper, we develop a Bayesian generalization of the SVM that jointly and simultaneously identifies the optimal nonlinear classifier and selects the optimal set of features (in this case, the genes involved in the diagnosis) via the optimization of a single posterior objective function. This joint classifier and feature optimization (JCFO) algorithm implements feature selection by first associating a positive scaling factor with the expression level of each gene. Then, during the training phase, along with the identification of the optimal classifier, the JCFO jointly estimates the optimal scaling factors with a strong prior preference for setting most of them to zero. Since setting the scaling factor for a gene to zero is equivalent to removing its effect on the classifier, the algorithm typically picks out only a handful of genes (typically around twenty in our experiments) that are actually used in the diagnosis. In the context of kernel classification, at an abstract level, a kernel classifier is simply a form of weighted voting based on the similarity of the gene expression profile of an unlabeled sample to the gene expression profiles of prototypical class examples that are identified during the classifier design. In the JCFO, this similarity between profiles as expressed in the kernel basis functions is determined using only the expression levels of the small subset of genes with nonzero scaling factors.

1.1. Related work

Our method differs in a couple of ways from earlier approaches that have been taken to the problem of identifying the genes that provide maximum diagnostic capability. Specifically, previous work has for the most part focused on the problem of feature selection in isolation from the problem of classifier design (the so-called filter approach to feature selection); typically, features (genes) are first selected, and then all those features are used to design a classifier for producing the diagnosis. One variation on this kind of approach is to perform dimensionality reduction before classification using PCA, SVD, linear discriminant analysis, or a related projection technique (West *et al.*, 2001). While projection techniques reduce the tendency towards overfitting in the context of high-dimensional data, they have the unfortunate property that they produce new predictors that are now linear (or in some cases nonlinear) combinations of all the genes at once, obviating the benefits of clinical deployability and mechanistic insights that might be associated with identifying a truly small set of *genes* useful for diagnosis. In contrast to methods using a filter approach to feature selection, other work has adopted the so-called wrapper approach (Weston *et al.*, 2000; Guyon *et al.*, 2002; Zhu and Hastie, 2002) in which the algorithm iterates between the problems of feature selection and classifier design.

Our approach is slightly different from both these approaches in that it involves solving these two problems at once. By combining the two problems of feature selection and classifier design and solving them together as part of a *joint* optimization, we seek to satisfy the most fundamental requirement of feature selection, namely, that we retain those features that are most useful in performing the classification itself. We address the feature selection problem by using sparsity-promoting priors as an integral part of the objective function used during the training procedure for designing the classifier, rather than as an external wrapper. This obviates the need to first select the genes that provide maximal diagnostic accuracy on the basis of a full leave-one-out cross-validation (LOOCV) study and then evaluate the accuracy of the resulting classifiers by performing another full LOOCV on the same data (see Ambroise and McLachlan, 2002).

Several algorithms proposed in the last few years—including the relevance vector machine (RVM) of Tipping (2001)—have used an automatic relevance determination (ARD) technique (Neal, 1996) for selecting either the features or the basis functions of the classifier during its training. More recently, Figueiredo and Jain have proposed an expectation maximization (EM) algorithm for sparse probit regression that achieves a similar result by maximizing a Bayesian *a posteriori* distribution (Figueiredo and Jain, 2001). While this algorithm does very well on a variety of pattern recognition benchmark problems, it only identifies an optimal classifier given a particular set of features. Other methods have used a framework of this sort to do automatic feature selection but only with direct hyperplane classifiers in the original feature space (nonkernelized) (Li *et al.*, 2002; Roth, 2003). The JCFO we propose here uses Bayesian priors to promote sparsity in *both* the selection of genes, as discussed above, *and* the basis functions used in the classifier, including the case where that classifier might be a kernel classifier. The JCFO extends the EM algorithm of Figueiredo and Jain (2001) by optimizing a Bayesian posterior to simultaneously obtain both the best classifier and the best feature scaling. Due to the close relationship between the JCFO and the algorithm of Figueiredo and Jain, we have deliberately tried where possible to preserve their notation in the interest of clarifying the presentation for the reader who may already be familiar with their work.

The remainder of this paper is structured as follows. In Section 2, we formalize the basic problem of pattern recognition in cancer diagnosis, introduce the notation used in the remainder of the paper, and discuss the broader context of the proposed approach, as well as its limitations. We introduce the novel JCFO algorithm in Section 3. In Section 4, we compare the performance of both the JCFO and the sparse probit regression algorithm of Figueiredo and Jain to current state-of-the-art classifiers (including the SVM and the RVM) on five widely used cancer diagnosis benchmark datasets. We conclude with a discussion of these results in Section 5.

2. PROBLEM FORMULATION

In the traditional pattern recognition literature, the problem of cancer diagnosis using the gene expression profile of a new tissue sample and a database of known gene expression profiles and their diagnoses falls under the general class of *supervised pattern recognition*. Given a database of training samples from N tissues, we have a set of N gene expression profiles $\mathbf{x}^{(i)}$ indexed by $i \in \{1, 2, ..., N\}$. Each expression profile $\mathbf{x}^{(i)} = [x_1^{(i)}, x_2^{(i)}, ..., x_d^{(i)}] \in \mathbb{R}^d$ is a d-dimensional vector representing the measured expression levels of d genes in the tissue sample. The class membership of each database sample is known and is denoted by $y^{(i)}$. In a two-class case (e.g., the tissues are either cancerous or noncancerous), we can assume without loss of generality that $y^{(i)} \in \{0, 1\}$. Thus, the training set D consists of N sets of expression profiles and their corresponding class membership labels.

$$D = \left\{ \left(\boldsymbol{x}^{(i)}, y^{(i)} \right) : \boldsymbol{x}^{(i)} \in \mathbb{R}^d, y^{(i)} \in \{0, 1\} \right\}_{i=1}^N$$
(1)

Assuming a parametric form for the functional relationship between x and y as $y = f_{\alpha}(x)$, during the training phase, we seek to find the optimal parameters α based on the evidence provided by the training data, D. In other words, in this formulation, we seek to learn a binary function $f_{\alpha}(\cdot) \colon \mathbb{R}^d \to \{0, 1\}$. This is the formulation adopted by the popular SVM classifier. However, it is often desirable not simply to classify x into one of two classes, but to know the degree of confidence for that classification. In such a case, we would be interested in learning a function $g_{\alpha}(x)$ taking values in the interval [0,1] (rather than just the set $\{0, 1\}$), which can be interpreted as the probability that x belongs to class 1, for example, in logistic regression

$$P(y = 1 | \mathbf{x}) = g_{\alpha}(\mathbf{x}) = \sigma \left(\alpha_0 + \sum_{l=1}^{d} \alpha_l x_l \right)$$
(2)

where $\sigma(z) = \{1 + \exp(-z)\}^{-1}$ is the logistic link function. The advantage of a classifier with a link function that gives class probabilities over a hard classifier like the SVM is that it can be used to obtain different optimal classifiers under different (possibly asymmetric) cost functions. In the case where the cost function is simply the misclassification error, a classifier can be obtained by thresholding $g_{\alpha}(x)$ at $\frac{1}{2}$.

In this paper, we consider classification functions of the form

$$P(y=1|\mathbf{x}) = g_{\alpha}(\mathbf{x}) = \Phi\left(\boldsymbol{\beta}^{T}\boldsymbol{h}_{\boldsymbol{\theta}}(\mathbf{x})\right)$$
(3)

where $\boldsymbol{\alpha} = [\boldsymbol{\beta}^T, \boldsymbol{\theta}^T]^T$ are the parameters to be learned, $\Phi(z)$ is the standard Gaussian cumulative distribution function (otherwise known as the probit link function),

$$\Phi(z) = \int_{-\infty}^{z} N(x|0, 1) \, dx = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{z} \exp\left(\frac{-x^2}{2}\right) dx,\tag{4}$$

and $h_{\theta}(x)$ is the vector whose scalar elements are the values of the basis functions for the classifier evaluated at x (we assume that the basis functions are parameterized by θ).

To illustrate the physical meaning of $h_{\theta}(x)$ more clearly, we consider three special cases of the general formulation that we have just outlined.

• Linear classifiers:

$$\boldsymbol{h}_{\boldsymbol{\theta}}(\boldsymbol{x}) = [1, x_1, \dots, x_d]^T.$$
(5)

For linear classifiers, the parameterization of the basis functions by θ is irrelevant. Note that in the case of symmetric misclassification costs, i.e., if we decide that y = 1 when $P(y = 1|x) = g_{\alpha}(x) > \frac{1}{2}$, $\beta^T h_{\theta}(x)$ represents the distance of the gene expression profile x from the classifying linear hyperplane. Here, the dimensionality of β is M = d + 1.

• Nonlinear classifiers:

$$\boldsymbol{h}_{\boldsymbol{\theta}}(\boldsymbol{x}) = [1, \psi_1(\boldsymbol{x}, \boldsymbol{\theta}), \dots, \psi_k(\boldsymbol{x}, \boldsymbol{\theta})]^T$$
(6)

where $\psi_j(\cdot)$ are k nonlinear basis functions of the classifier. Here, the dimensionality of β is M = k + 1and for symmetric misclassification costs, $\beta^T h_{\theta}(x)$ represents the distance of the gene expression profile x from the classifying linear hyperplane in the ψ -space. In other words, the nonlinear classification problem in the original feature space (i.e., x-space) is transformed into a linear classification problem into another space using the nonlinear vector mapping function between the two spaces $h_{\theta}(x)$.

• Kernel classifiers:

$$\boldsymbol{h}_{\boldsymbol{\theta}}(\boldsymbol{x}) = \left[1, K_{\boldsymbol{\theta}}(\boldsymbol{x}, \boldsymbol{x}^{(1)}), \dots, K_{\boldsymbol{\theta}}(\boldsymbol{x}, \boldsymbol{x}^{(N)})\right]^{T}$$
(7)

where $K_{\theta}(x, x^{(i)})$ is some symmetric kernel function parameterized by θ (Cristianini and Shawe-Taylor, 2000). Figure 1 depicts the kernel mapping between the feature space containing x and the kernel space containing $h_{\theta}(x)$. The kernel basis function $K_{\theta}(x, x^{(i)})$ provides a nonlinear measure of similarity between the gene expression levels of a new unlabeled sample x and a labeled sample from our training database $x^{(i)}$. Here, the dimensionality of β is M = N + 1. Kernel basis functions are used in the SVM.

In this paper, we will use the parameter vector $\boldsymbol{\theta}$ to represent the scaling factors associated with the genes. Thus, the dimensionality of $\boldsymbol{\theta}$ is d, and we can write $\boldsymbol{\theta} = [\theta_1, \theta_2, \dots, \theta_d]^T \in \mathbb{R}^d$. Specifically, if $\theta_l = 0$, then our diagnostic classifier does not use any information about the expression level of the *l*-th gene in the process of making its decision.

While the SVM requires special restrictions to be placed on the kernel function for the kernel to be admissible in the training procedure— $K_{\theta}(\cdot, \cdot)$ has to be a Mercer kernel—the JCFO does not have any such requirements, and the same is true of the RVM and sparse probit regression algorithms as well. In the research presented in this paper, we have used *n*-th order polynomial kernels in our experiments:

$$K_{\boldsymbol{\theta}}(\boldsymbol{x}, \boldsymbol{x}^{(i)}) = \left(1 + \sum_{l=1}^{d} \theta_l x_l x_l^{(i)}\right)^n.$$
(8)



FIG. 1. Kernel mapping: a vector x in the feature space of d dimensions is mapped by $h_{\theta}(\cdot)$ into a vector $h_{\theta}(x)$ in the kernel space of N dimensions, which is spanned by the N kernel basis functions.

In this paper, we seek to find classifiers (i.e., to find values of β and θ) that not only diagnose the presence or absence of cancer accurately, but also do so with very few nonzero elements in either β or θ . Sparsity in β implies that the classifier finds a small subset of prototypical samples that are highly representative of the different classes we seek to distinguish, while sparsity in θ implies that it implicitly performs feature selection (i.e., it identifies the genes important for the diagnosis).

2.1. Bayesian pattern recognition

Our solution can be summarized as follows: the problems of classifier design and feature selection can be viewed together as the single problem of estimating the best parameters $\boldsymbol{\alpha} = [\boldsymbol{\beta}^T, \boldsymbol{\theta}^T]^T$ from limited data. In order to obtain good *generalization* (i.e., to perform well on new data not seen during training), we need to control the complexity of the learned classifier function. Specifically, we need to guard against two potential problems: if the classifier is too complex it may "learn" irrelevant properties of the particular dataset on which it is trained, and not perform well on as-yet-unseen data (*overfitting*); on the other hand, if the classifier is too simple, then we may be unable to effectively capture the essential structure of the underlying relationship (*underfitting*). In a Bayesian approach, we solve this problem by introducing some kind of prior knowledge into the design phase.

More precisely, we accomplish this by choosing prior probability distributions over the parameters β and θ to reflect our (subjective) beliefs about them before seeing any data. In our case, we choose priors that reflect our belief that both β and θ are sparse, i.e., $P(\beta, \theta)$ is large when most of these parameters are exactly zero (as opposed to being *nearly* zero). This suggests that the prior distributions must drop off very fast as the parameters β and θ move away from zero, making density functions that are smoothly differentiable at zero—like the Gaussian—inappropriate.

After seeing the data D, we can use Bayes rule to obtain a posterior distribution $P(\beta, \theta|D)$. The posterior will reflect our final opinion about β and θ , taking into account both our prior subjective knowledge (sparsity of the solution) and the evidence provided by the data. Thus, the optimal classifier can be identified by finding the maximum *a posteriori* (MAP) estimate of β and θ .

The problem, however, is that finding the MAP value of the posterior for our parameters can be a computationally expensive task if we choose arbitrary sparsity-promoting priors. In general, we would be forced to adopt expensive MCMC techniques. However, our algorithm builds upon the prior work of Figueiredo and Jain (2001) and Tipping (2001), both of whom have developed methods to find a sparse estimate of β under certain forms of the prior. In particular, we extend the algorithm of Figueiredo and Jain to jointly design the classifier and the feature scaling, i.e., to estimate β and θ .

In this paper, we choose a Laplacian prior that allows us to design an elegant EM algorithm to find a maximum of the posterior probability density. Using an EM algorithm to optimize the posterior probability immediately raises the concern that any maximum we find may be simply a local rather than global

maximum. To investigate this, we have sampled the Hessian of the objective function at a large number of points to test for positive definiteness, and based on this sampling, believe that our objective function has only a single global maximum, at least for polynomial kernels. However, we do not yet have an analytical proof of this, and sampling evidence can never be conclusive since it is possible that we may have inadvertently sampled in a limited region in which the Hessian is positive definite. Regardless of whether the posterior maximum we reach is local or global, our experiments on the five widely used benchmark datasets in Section 4 indicate that the JCFO has better diagnostic classification accuracy than other current state-of-the-art methods reported in the literature.

Finally, it is worth noting that sparsity in β for kernel classifiers is known to be an important indicator of the *capacity* of the classifier, which measures its generalization. As is evident from the curse of dimensionality, sparsity in the features as governed by θ is also an important factor in increasing the robustness of the classifier design. Thus, our choice of sparsity-promoting priors reflects our desire to obtain a robust classifier that performs well on as-yet-unseen test data.

3. JOINT CLASSIFIER AND FEATURE OPTIMIZATION

As the first step of our Bayesian analysis, we have to specify the prior on the parameters β and θ that we want to estimate. We choose to adopt a Laplacian prior on β , since it is known from earlier work that this prior promotes sparsity (making several $\beta_i = 0$) due to its use of the l_1 norm (or lasso) penalty:

$$P(\boldsymbol{\beta}|\eta) = \prod_{i=1}^{M} \frac{\eta}{2} \exp(-\eta |\beta_i|) = \left(\frac{\eta}{2}\right)^{M} \exp(-\eta \|\boldsymbol{\beta}\|_{1}).$$
(9)

Figure 2 illustrates this property of a Laplacian prior, and contrasts it with a Gaussian prior, whose derivative at zero is zero. As the figure illustrates, the difference between P(0) and $P(\beta_i)$ for small β_i is much larger for a Laplacian than for a Gaussian. As a result, if we use a Laplacian prior, learning procedures that seek to maximize the posterior would explicitly favor values of β_i that are exactly 0 instead of small values close to 0, thus promoting sparsity in β . Methods that control model complexity using a Laplacian prior (or equivalently, an l_1 or lasso penalty) have become quite popular recently (see Tibshirani, 1996; Figueiredo and Jain, 2001; Fung and Mangasarian, 2002; Rosset *et al.*, 2003; Roth, 2003) and are theoretically well-justified (see Friedman *et al.*, 2004; Donoho and Elad, 2002 and references therein).

If we attempt to use a Laplacian prior directly, we run into computational difficulties. However, equivalently, we may instead use the two-level hierarchical model described below, which corresponds to an



FIG. 2. Sparsity-promoting Laplacian prior: the Laplacian distribution is sharply peaked and not smoothly differentiable about zero, unlike the Gaussian distribution, which is everywhere smoothly differentiable and whose derivative at zero is zero.

effective Laplacian prior. Under such a model, each β_i is given a zero-mean Gaussian prior with its own variance τ_i :

$$P(\beta_i | \tau_i) = N(\beta_i | 0, \tau_i). \tag{10}$$

If we further suppose the variances τ_i to have an exponential distribution as their hyperprior,

$$P(\tau_i|\gamma_1) = \frac{\gamma_1}{2} \exp\left(-\frac{\gamma_1 \tau_i}{2}\right), \text{ for } \tau_i \ge 0,$$
(11)

then the effective prior can be obtained by integrating out τ_i ,

$$P(\beta_i|\gamma_1) = \int_0^\infty P(\beta_i|\tau_i) P(\tau_i|\gamma_1) d\tau_i = \frac{\sqrt{\gamma_1}}{2} \exp(-\sqrt{\gamma_1}|\beta_i|), \qquad (12)$$

which shows that a Laplacian prior is equivalent to a two-level hierarchical model characterized by zeromean Gaussian priors with independent variances and an exponential hyperprior for those variances.

In estimating the parameter θ_i , we can adopt a prior that is similar to that for β_i but differs in one critical aspect: we must ensure that our algorithms learn $\theta_i \ge 0$. The reason for this requirement is somewhat subtle. Essentially, θ_i measures the scaling of the individual genes. In the forms of the kernels that we have described in Equation (8), using a negative scaling θ_i effectively implies that if we compare two gene expression profiles using these kernels, similar levels of expression profiles. Though greater similarity of a particular gene's expression levels in two different expression profiles need not necessarily imply that these two expression profiles are *more* similar (in the context of diagnostic classification, especially when the particular gene is irrelevant for the diagnosis), it can never imply that the profiles are somehow *less* similar. Thus, even though θ_i can be exactly zero, it can never be negative. As a result, we consider a two-level hierarchical model for θ_i that explicitly makes them nonnegative. In particular, we adopt nonnegative Gaussian priors on θ_i with independent variances given by ρ_i , and exponential priors on ρ_i . This is described below:

$$P(\theta_i|\rho_i) = \begin{cases} 2N(\theta_i|0,\rho_i) & \text{if } \theta_i \ge 0\\ 0 & \text{if } \theta_i < 0 \end{cases}$$
(13)

$$P(\rho_i|\gamma_2) = \frac{\gamma_2}{2} \exp\left(-\frac{\gamma_2 \rho_i}{2}\right), \text{ for } \rho_i \ge 0.$$
(14)

Thus, the effective prior on θ_i is

$$P(\theta_i|\gamma_2) = \begin{cases} \sqrt{\gamma_2} \exp(-\sqrt{\gamma_2}\theta_i) & \text{if } \theta_i \ge 0\\ 0 & \text{if } \theta_i < 0. \end{cases}$$
(15)

3.1. EM estimation of MAP parameters

Having specified the priors on the parameters that we seek to estimate, we can now proceed to the description of an EM algorithm that finds a (possibly local) maximum of the posterior distribution over β and θ . To motivate the development of the algorithm, let us consider the latent variable interpretation of the probit link function, as exploited by Albert and Chib (1993) and, subsequently, by Figueiredo and Jain (2001).

Let $z(\mathbf{x}, \boldsymbol{\beta}, \boldsymbol{\theta}) = \boldsymbol{\beta}^T \boldsymbol{h}_{\boldsymbol{\theta}}(\mathbf{x}) + w$, where w is a zero-mean unit-variance Gaussian random variable. If the classifier is defined as y = 1 for $z(\mathbf{x}, \boldsymbol{\beta}, \boldsymbol{\theta}) \ge 0$ and y = 0 for $z(\mathbf{x}, \boldsymbol{\beta}, \boldsymbol{\theta}) < 0$, then we recover the probit model, because

$$P(y = 1 | \mathbf{x}) = P\left(\boldsymbol{\beta}^T \boldsymbol{h}_{\boldsymbol{\theta}}(\mathbf{x}) + w > 0\right)$$

= $\Phi\left(\boldsymbol{\beta}^T \boldsymbol{h}_{\boldsymbol{\theta}}(\mathbf{x})\right).$ (16)

Figure 3 provides a graphical depiction of the intuition behind this interpretation.



FIG. 3. Latent variable interpretation of z: the variable z represents the distance in kernel space between the sample and the hyperplane describing the classifier (parameterized by β). The probit link function provides the probability of belonging to a particular class, so class membership is determined by the sign of z.

Given data $D = \{ \langle \mathbf{x}^{(i)}, y^{(i)} \rangle : \mathbf{x}^{(i)} \in \mathbb{R}^d, y^{(i)} \in \{0, 1\} \}_{i=1}^N$, consider the corresponding vector of missing variables $\mathbf{z} = [z^{(1)}, z^{(2)}, \dots, z^{(N)}]^T$, as well as the vectors of missing variables $\mathbf{\tau} = [\tau_1, \tau_2, \dots, \tau_M]^T$ and $\boldsymbol{\rho} = [\rho_1, \rho_2, \dots, \rho_d]^T$. If we knew the values of $\mathbf{z}, \mathbf{\tau}$, and $\boldsymbol{\rho}$, we would have an easier estimation problem for $\boldsymbol{\beta}$ and $\boldsymbol{\theta}$ since we would effectively only have to find the maximum *a posteriori* solution for the following system of equations under Gaussian priors:

$$\boldsymbol{z} = \boldsymbol{H}_{\boldsymbol{\theta}}\boldsymbol{\beta} + \boldsymbol{w} \tag{17}$$

where $H_{\theta} = [h_{\theta}(x^{(1)}), h_{\theta}(x^{(2)}), \dots, h_{\theta}(x^{(N)})]^T$ is known as the design matrix and w is a vector of i.i.d. zero-mean unit-variance Gaussian samples. This suggests the use of an EM algorithm to find a locally maximum *a posteriori* estimate of β and θ . We consider z, τ , and ρ as hidden variables and β and θ as the parameters to be estimated. The EM algorithm will produce a sequence of estimates for $\hat{\beta}^{(t)}$ and $\hat{\theta}^{(t)}$ by alternating between two steps:

E-step: The log-posterior on the parameters that we seek to estimate (here β , θ) given the data D and the hidden variables (here z, τ , and ρ), is $\log(P(\beta, \theta | y, z, \tau, \rho))$. In the E-step, we compute the expected value of this log-posterior conditioned on the data D and the current estimate of the parameters, $\hat{\beta}^{(t)}$, $\hat{\theta}^{(t)}$. This is usually denoted as the Q function:

$$Q\left(\boldsymbol{\beta},\boldsymbol{\theta} \mid \hat{\boldsymbol{\beta}}^{(t)}, \hat{\boldsymbol{\theta}}^{(t)}\right) = \int P\left(\boldsymbol{z},\boldsymbol{\tau},\boldsymbol{\rho} \mid \boldsymbol{y}, \hat{\boldsymbol{\beta}}^{(t)}, \hat{\boldsymbol{\theta}}^{(t)}\right) \times \log P(\boldsymbol{\beta},\boldsymbol{\theta}|\boldsymbol{y},\boldsymbol{z},\boldsymbol{\tau},\boldsymbol{\rho}) \, d\boldsymbol{z} d\boldsymbol{\tau} d\boldsymbol{\rho}.$$
(18)

M-step: Update the current parameter estimate according to

$$\hat{\boldsymbol{\beta}}^{(t+1)}, \hat{\boldsymbol{\theta}}^{(t+1)} = \underset{\boldsymbol{\beta}, \boldsymbol{\theta}}{\arg \max} Q\left(\boldsymbol{\beta}, \boldsymbol{\theta} \mid \hat{\boldsymbol{\beta}}^{(t)}, \hat{\boldsymbol{\theta}}^{(t)}\right).$$
(19)

In what follows, we drop the θ subscripts on the H and h terms to simplify the notation. As a first step, we see that the complete log-posterior on the learning parameters β and θ , including the hidden

variables z, τ , and ρ , is

$$\log P(\boldsymbol{\beta}, \boldsymbol{\theta} | \boldsymbol{y}, \boldsymbol{z}, \boldsymbol{\tau}, \boldsymbol{\rho}) = \log P(\boldsymbol{z} | \boldsymbol{\beta}, \boldsymbol{\theta}) + \log P(\boldsymbol{\beta} | \boldsymbol{\tau}) + \log P(\boldsymbol{\theta} | \boldsymbol{\rho}) + c$$
$$= - \|\boldsymbol{H}\boldsymbol{\beta} - \boldsymbol{z}\|^2 - \boldsymbol{\beta}^T \boldsymbol{T}\boldsymbol{\beta} - \boldsymbol{\theta}^T \boldsymbol{R}\boldsymbol{\theta} + c$$
$$= -\boldsymbol{z}^T \boldsymbol{z} - \boldsymbol{\beta}^T \boldsymbol{H}^T (\boldsymbol{H}\boldsymbol{\beta} - 2\boldsymbol{z}) - \boldsymbol{\beta}^T \boldsymbol{T}\boldsymbol{\beta} - \boldsymbol{\theta}^T \boldsymbol{R}\boldsymbol{\theta} + c$$
(20)

where the matrix $\mathbf{T} = diag(\tau_1^{-1}, \tau_2^{-1}, \dots, \tau_M^{-1})$, the matrix $\mathbf{R} = diag(\rho_1^{-1}, \rho_2^{-1}, \dots, \rho_d^{-1})$, and c is a constant that can be ignored. Thus, the Q function is

$$Q\left(\boldsymbol{\beta},\boldsymbol{\theta}\mid \hat{\boldsymbol{\beta}}^{(t)}, \hat{\boldsymbol{\theta}}^{(t)}\right) = E\left[-\boldsymbol{z}^{T}\boldsymbol{z} - \boldsymbol{\beta}^{T}\boldsymbol{H}^{T}(\boldsymbol{H}\boldsymbol{\beta} - 2\boldsymbol{z}) - \boldsymbol{\beta}^{T}\boldsymbol{T}\boldsymbol{\beta} - \boldsymbol{\theta}^{T}\boldsymbol{R}\boldsymbol{\theta}\mid \boldsymbol{y}, \hat{\boldsymbol{\beta}}^{(t)}, \hat{\boldsymbol{\theta}}^{(t)}\right].$$
(21)

Since we seek to maximize the Q function w.r.t. $\boldsymbol{\beta}$ and $\boldsymbol{\theta}$ in the EM algorithm, terms like $E[-z^T z \mid y, \hat{\boldsymbol{\beta}}^{(t)}, \hat{\boldsymbol{\theta}}^{(t)}]$ that do not involve $\boldsymbol{\beta}$ or $\boldsymbol{\theta}$ can be effectively ignored in the M-step, and thus are irrelevant in the E-step as well. Therefore, the Q function simplifies to

$$Q\left(\boldsymbol{\beta},\boldsymbol{\theta} \mid \hat{\boldsymbol{\beta}}^{(t)}, \hat{\boldsymbol{\theta}}^{(t)}\right) = -\boldsymbol{\beta}^{T} \boldsymbol{H}^{T} \boldsymbol{H} \boldsymbol{\beta} + 2\boldsymbol{\beta}^{T} \boldsymbol{H}^{T} \boldsymbol{E} \left[\boldsymbol{z} \mid \boldsymbol{y}, \hat{\boldsymbol{\beta}}^{(t)}, \hat{\boldsymbol{\theta}}^{(t)}\right] - \boldsymbol{\beta}^{T} \boldsymbol{E} \left[\boldsymbol{T} \mid \boldsymbol{y}, \hat{\boldsymbol{\beta}}^{(t)}, \hat{\boldsymbol{\theta}}^{(t)}\right] \boldsymbol{\beta} - \boldsymbol{\theta}^{T} \boldsymbol{E} \left[\boldsymbol{R} \mid \boldsymbol{y}, \hat{\boldsymbol{\beta}}^{(t)}, \hat{\boldsymbol{\theta}}^{(t)}\right] \boldsymbol{\theta}.$$
(22)

The E-step thus simplifies to computing the expectations associated with each of these terms. Fortunately, each of these computations can be expressed in closed form. As for the term associated with the expectation of z, we have

$$v_{i} = E\left[z^{(i)} \mid \mathbf{y}, \hat{\boldsymbol{\beta}}^{(t)}, \hat{\boldsymbol{\theta}}^{(t)}\right] = \begin{cases} \boldsymbol{h}^{T}(\boldsymbol{x}^{(i)})\hat{\boldsymbol{\beta}}^{(t)} + \frac{N\left(\boldsymbol{h}^{T}(\boldsymbol{x}^{(i)})\hat{\boldsymbol{\beta}}^{(t)} \mid 0, 1\right)}{1 - \Phi\left(-\boldsymbol{h}^{T}(\boldsymbol{x}^{(i)})\hat{\boldsymbol{\beta}}^{(t)}\right)}, & \text{if } y^{(i)} = 1\\ \boldsymbol{h}^{T}(\boldsymbol{x}^{(i)})\hat{\boldsymbol{\beta}}^{(t)} - \frac{N\left(\boldsymbol{h}^{T}(\boldsymbol{x}^{(i)})\hat{\boldsymbol{\beta}}^{(t)} \mid 0, 1\right)}{\Phi\left(-\boldsymbol{h}^{T}(\boldsymbol{x}^{(i)})\hat{\boldsymbol{\beta}}^{(t)}\right)}, & \text{if } y^{(i)} = 0 \end{cases}$$
(23)

which follows from the observation that $z^{(i)}$ is distributed as a Gaussian with mean $h^T(\mathbf{x}^{(i)})\hat{\boldsymbol{\beta}}^{(t)}$, but left-truncated at zero if $y^{(i)} = 1$ and right-truncated at zero if $y^{(i)} = 0$. After some further algebraic manipulations, it can be shown that for the term associated with the expectation of T, we have

$$\omega_{i} = E\left[\tau_{i}^{-1} \mid \mathbf{y}, \hat{\boldsymbol{\beta}}_{i}^{(t)}, \gamma_{1}\right] = \frac{\int_{0}^{\infty} \tau_{i}^{-1} P(\tau_{i} \mid \gamma_{1}) P\left(\hat{\boldsymbol{\beta}}_{i}^{(t)} \mid \tau_{i}\right) d\tau_{i}}{\int_{0}^{\infty} P(\tau_{i} \mid \gamma_{1}) P\left(\hat{\boldsymbol{\beta}}_{i}^{(t)} \mid \tau_{i}\right) d\tau_{i}} = \gamma_{1} \left|\hat{\boldsymbol{\beta}}_{i}^{(t)}\right|^{-1}.$$
(24)

The last term in the E-step computation is associated with the expectation of R, and a manipulation similar to that above yields the following:

$$\delta_i = E\left[\rho_i^{-1} \mid \mathbf{y}, \hat{\boldsymbol{\theta}}_i^{(t)}, \gamma_2\right] = \gamma_2 \left(\hat{\boldsymbol{\theta}}_i^{(t)}\right)^{-1}.$$
(25)

Note that our prior on θ requires that each θ_i be nonnegative, so we employ a constrained optimization here to ensure that this remains true. If θ_i becomes exactly zero for some values of *i*, we can simply prune those features and continue with the remainder of the optimization.

KRISHNAPURAM ET AL.

In summary, all three integrations required for the expectation terms in the E-step can be done analytically. If we define $\mathbf{v} = [v_1, v_2, \dots, v_N]^T$, $\mathbf{\Omega} = diag(\omega_1, \omega_2, \dots, \omega_M)$, and $\mathbf{\Delta} = diag(\delta_1, \delta_2, \dots, \delta_d)$, then in the M-step we have to maximize the following Q function with respect to $\boldsymbol{\beta}$ and $\boldsymbol{\theta}$ jointly:

$$Q\left(\boldsymbol{\beta},\boldsymbol{\theta} \mid \hat{\boldsymbol{\beta}}^{(t)}, \hat{\boldsymbol{\theta}}^{(t)}\right) = -\boldsymbol{\beta}^{T} \boldsymbol{H}^{T} \boldsymbol{H} \boldsymbol{\beta} + 2\boldsymbol{\beta}^{T} \boldsymbol{H}^{T} \boldsymbol{v} - \boldsymbol{\beta}^{T} \boldsymbol{\Omega} \boldsymbol{\beta} - \boldsymbol{\theta}^{T} \boldsymbol{\Delta} \boldsymbol{\theta},$$
(26)

$$\frac{\partial Q}{\partial \boldsymbol{\beta}} = 2\boldsymbol{H}^T \boldsymbol{v} - 2\boldsymbol{H}^T \boldsymbol{H} \boldsymbol{\beta} - 2\boldsymbol{\Omega} \boldsymbol{\beta}, \tag{27}$$

$$\frac{\partial Q}{\partial \theta_l} = -2\delta_l \theta_l - 2\sum_{n=1}^N \sum_{m=1}^M \left\{ (\boldsymbol{H}\boldsymbol{\beta} - \boldsymbol{v})\boldsymbol{\beta}^T \odot \left(\frac{\partial \boldsymbol{H}}{\partial \theta_l}\right) \right\}_{(i,j)},$$
(28)

where \odot represents the element-wise matrix Hadamard product. In this paper, we have primarily used polynomial kernel classifiers of the form given in Equation (8) so that $H_{i,1} = 1$ and $H_{i,(j+1)} = (1 + \sum_{l=1}^{d} \theta_l x_l^{(i)} x_l^{(j)})^n$. This means that $\frac{\partial H_{i,1}}{\partial \theta_l} = 0$, and $\frac{\partial H_{i,(j+1)}}{\partial \theta_l} = n x_l^{(i)} x_l^{(j)} (1 + \sum_{l=1}^{d} \theta_l x_l^{(i)} x_l^{(j)})^{n-1}$ for j = 1, 2, ..., N.

Since H is in general a nonlinear function of θ , Q is also highly nonlinear and cannot be maximized analytically. Moreover, the optimization of β and θ cannot be pursued independently. However, we can exploit the fact that for any given θ , the optimal β_{θ} corresponding to it can be evaluated analytically by setting $\frac{\partial Q}{\partial \beta} = 0$ above. Thus, we have

$$\hat{\boldsymbol{\beta}_{\theta}}^{(t+1)} = (\boldsymbol{\Omega} + \boldsymbol{H}^{T}\boldsymbol{H})^{-1}\boldsymbol{H}^{T}\boldsymbol{v}$$

$$= \kappa(\boldsymbol{I} + \kappa\boldsymbol{H}^{T}\boldsymbol{H}\kappa)^{-1}\kappa\boldsymbol{H}^{T}\boldsymbol{v}$$
(29)

where $\kappa = diag(k_1, k_2, ..., k_M)$ and its diagonal entries are $k_i = \omega_i^{-1/2} = \gamma_1^{-1/2} |\hat{\beta}_i^{(t)}|^{1/2}$. The matrix κ has been introduced to enable a stable numerical implementation, which is necessary since the sparsity-promoting properties of the hierarchical priors will drive several of the β_i to zero, thereby causing numerical instabilities in any implementation using Ω directly.

Although $\hat{\boldsymbol{\beta}}^{(t+1)}$ can be computed straightforwardly, we are forced to employ numerical nonlinear optimization techniques to obtain $\hat{\boldsymbol{\theta}}^{(t+1)}$ from the M-step. In our research, we have used the implementation of a subspace trust region method that is contained in the Matlab optimization toolbox and is based on the interior-reflective Newton method of Coleman and Li (1996). This is an iterative method, each iteration of which involves the approximate solution of a large linear system using the method of preconditioned conjugate gradients. This method also requires that we provide the derivatives of the Q function with respect to $\boldsymbol{\theta}$, which we have computed in Equation (28).

We summarize the full algorithm in the subsection below for clarity.

3.2. Summary of the JCFO algorithm

- 1. Given the training set D, use an initial uninformative scaling of $\theta_i = 1$ for all the features to compute the initial design matrix **H**.
- 2. Using the initial design matrix H, compute an initial seed estimate for β using a weakly penalized ridge regression with the labels as data. In other words, compute $\beta = (\varepsilon I + H^T H)^{-1} H y$ with a suitably small ε (we have used 10^{-6} in our experiments). Note that this corresponds to a weak zero-mean Gaussian prior with a very large variance for each of the elements of β .
- 3. Using the initial seed estimate for β and the initial uninformative scaling θ , compute the priors Ω and Δ using Equations (24) and (25), respectively.
- 4. With the above $\boldsymbol{\beta}$ and $\boldsymbol{\theta}$ as a starting point, use a nonlinear optimization technique to find the values of $\hat{\boldsymbol{\beta}}^{(0)}$ and $\hat{\boldsymbol{\theta}}^{(0)}$ that maximize (26). This provides a suitable starting point for the EM algorithm below.
- 5. *E-Step*: Given the current estimates for $\hat{\boldsymbol{\beta}}^{(t)}$ and $\hat{\boldsymbol{\theta}}^{(t)}$, update the values of \boldsymbol{v} , $\boldsymbol{\Omega}$, and $\boldsymbol{\Delta}$ using Equations (23), (24), and (25), respectively.
- 6. *M-Step*: Obtain the new estimates $\hat{\boldsymbol{\beta}}^{(t+1)}$ and $\hat{\boldsymbol{\theta}}^{(t+1)}$ using the values of \boldsymbol{v} , $\boldsymbol{\Omega}$, and $\boldsymbol{\Delta}$ from the E-step by maximizing (26).
- 7. Repeat steps 5 and 6 until convergence of the log-posterior.

Note that we must employ a constrained optimization in steps 4 and 6 to ensure satisfaction of the linear inequality constraints $\theta_i \ge 0$. Also, note that if we use a linear classifier with the formulation for h given in Equation (5), then we have a fixed θ and, consequently, our M-step simply reduces to Equation (29). In this case, no nonlinear optimization would be required, but the sparsity of β would still ensure that we use the expression levels of very few genes in designing a hyperplane classifier. We have used this version as a fast but powerful feature selection algorithm to reduce the dimensionality of the data that has to be handled by the JCFO with a linear (i.e., polynomial order 1) kernel. Thus, we can first perform the feature selection using exactly the same algorithm by simply changing our design matrix and keeping θ constant; this procedure typically identifies about 50 genes to be of relevance (nonzero scaling). Then, we can quickly run the JCFO since the dimensionality of the search space for the nonlinear optimization in the M-step is much smaller (and thus the search is much faster).

It should be observed that although both the JCFO with a linear kernel and the simpler version above using (5) construct sparse hyperplane classifiers, they will be expected to perform differently due to the different priors on each model. Using (5), we have sparsity in the features but not in the kernel coefficients, while the JCFO still has both kinds of sparsity. Since this affords an extra amount of regularization, we have observed greater classification accuracy for the JCFO, even though both methods construct hyperplane classifiers.

4. EXPERIMENTAL RESULTS

In this paper, while we are the first to apply the sparse probit regression algorithm of Figueiredo and Jain to the problem of classifying gene expression data, our primary contribution is the development and application of the JCFO algorithm. To gauge the efficacy of these algorithms in comparison with a number of others, we tested them on two benchmark cancer datasets and three breast cancer datasets; all the datasets provide expression levels for human genes produced by Affymetrix high-density oligonucleotide microarrays. To measure diagnostic accuracy, we use a full leave-one-out cross-validation procedure (LOOCV) where we train on N - 1 samples and test on the remaining sample which has not been used during training. By cycling through all the samples, we can get realistic and honest estimates of the accuracy of these methods. In all our experiments, we normalize the expression levels for each gene by subtracting the mean and dividing by the standard deviation of that gene. The hyperparameters γ_1 and γ_2 of the JCFO were adjusted in each cycle of the LOOCV by using a hold-out test set of 10% of the data; the chosen values were then used with the entire dataset to obtain the classifiers for that cycle of the LOOCV. The regularization constant of the SVM was chosen similarly.

In order to reduce the computational cost of the full LOOCV procedure, we accelerated our JCFO feature selection in each cycle of the LOOCV by preprocessing using the JCFO algorithm with a linear h function of the form given in Equation (5), as explained above. Thus, we were able to perform the complete LOOCV error rate estimation for the JCFO on an 800MHz Pentium III Windows machine within a couple of hours, by taking advantage of the reduction in dimensionality of the search space for the general nonlinear optimization. It is worth pointing out that we did *not* preselect features first by using a LOOCV and then performing the classification. Instead, the above two-step process was simply a proxy for a single, larger optimization problem.

We first examined two benchmark cancer datasets reported in the literature to evaluate the ability of different classification methods to recover clinical outcomes. The first bench mark dataset contains examples of human acute leukemia, originally analyzed by Golub *et al.* (1999). The dataset containing expression levels of 7,129 genes can be obtained at *www-genome.wi.mit.edu/mpr/table_AML_ALL_samples.rtf*. To collect this data, bone marrow or blood samples were taken from 72 patients, 47 with acute myeloid leukemia (AML) and 25 with acute lymphoblastic leukemia (ALL). The second benchmark dataset contains expression levels of 2,000 genes from 40 tumor and 22 normal colon tissues. The dataset was originally analyzed by Alon *et al.* (1999) and was downloaded from *www.molbio.princeton.edu/colondata*.

In Table 1, we present a full leave-one-out cross-validation study for each of the two benchmark datasets to compare the accuracy of the diagnostic classification reported by the JCFO against that reported by Adaboosting, the SVM, the RVM, logistic regression, and sparse probit regression. For kernel classifiers, low-degree polynomial kernels were chosen because previous literature has indicated these to be most accurate for these gene expression datasets; in particular, linear kernels have been found to work

Classifier	AML/ALL	Colon tumor
Adaboosting (decision stumps) ^a	95.8	72.6
SVM (quadratic kernel) ^a	95.8	74.2
SVM (linear kernel) ^a	94.4	77.4
RVM (linear kernel)	94.4	80.6
RVM (no kernel: on feature space) ^b	97.2	88.7
Logistic regression (no kernel: on feature space) ^b	97.2	71.0
Sparse probit regression (quadratic kernel)	95.8	84.6
Sparse probit regression (linear kernel)	97.2	91.9
Sparse probit regression (no kernel: on feature space)	97.2	85.5
JCFO (quadratic kernel)	98.6	88.7
JCFO (linear kernel)	100.0	96.8

TABLE 1. ACCURACY OF DIAGNOSTIC CLASSIFICATION: MULTIPLE CLASSIFIERS APPLIEDTO TWO BENCHMARK CANCER DATASETS (% CORRECT IN LOOCV STUDY)

^aBen-Dor et al., 2000.

^bKrishnapuram et al., 2002.

indel 2. mooi imonini olined for distinction nell, no deletted di me del	TABLE 2.	Most Important	GENES FOR DI	STINGUISHING AM	IL FROM ALL.	AS SELECTED	BY THE JCFO
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$\boldsymbol{\theta}_i$	Index	Accession	Gene name	Gene description
1.14	1780	M19507	MPO	myeloperoxidase
0.83	3848	U82759	HOXA9	homeo box A9
0.81	1797	M20902	APOC1	apolipoprotein C-I
0.77	1830	M22960	PPGB	protective protein for beta-galactosidase (galactosialidosis)
0.70	4952	Y07604	NME4	non-metastatic cells 4, protein expressed in
0.67	5599	L15326	PTGS2	prostaglandin-endoperoxide synthase 2
0.56	5003	Y10207	CD171	Human CD171 protein
0.51	5108	Z29067	NEK3	NIMA (never in mitosis gene a)-related kinase 3
0.46	1883	M27891	CST3	cystatin C (amyloid angiopathy and cerebral hemorrhage)
0.42	6540	X85116	EPB72	erythrocyte membrane protein band 7.2 (stomatin)
0.42	2289	M84526	DF	D component of complement (adipsin)
0.41	6185	M14483	PTMA	prothymosin, alpha (gene sequence 28)
0.41	879	Y00371	HSPA8	heat shock 70kDa protein 8
0.40	5349	M61853	CYP2C18	cytochrome P450, subfamily IIC, polypeptide 18
0.35	1835	M23197	CD33	CD33 antigen (gp67)
0.34	4197	X17042	PRG1	proteoglycan 1, secretory granule
0.33	6170	M13690	SERPING1	serine (or cysteine) proteinase inhibitor, clade G, member 1
0.32	1395	L20941	FTH1	ferritin, heavy polypeptide 1
0.30	1942	M31994	ALDH1A1	aldehyde dehydrogenase 1 family, member A1
0.29	3321	U50136	LTC4S	leukotriene C4 synthase
0.27	5767	X13294	MYBL1	v-myb myeloblastosis viral oncogene homolog (avian)-like 1
0.26	1976	J02963	ITGA2B	integrin, alpha 2b (platelet glycoprotein IIb, antigen CD41B)
0.23	805	HG1612	MACMARCKS	macrophage myristoylated alanine-rich C kinase substrate
0.18	6056	U28055	MST1	macrophage stimulating 1 (hepatocyte growth factor-like)
0.16	2122	M63138	CTSD	cathepsin D (lysosomal aspartyl protease)
0.16	1934	M31627	XBP1	X-box binding protein 1
0.12	3392	U53468	NDUFA5	NADH dehydrogenase (ubiquinone) 1 alpha subcomplex, 5, 13kDa
0.08	3715	U77604	MGST2	microsomal glutathione S-transferase 2
0.07	6226	M28170	CD19	CD19 antigen
0.03	1686	M11722	DNTT	deoxynucleotidyltransferase, terminal

$\boldsymbol{\theta}_i$	Index	Accession	Gene name	Gene description
2.10	1357	T84051	CDC42	cell division cycle 42 (GTP binding protein, 25kDa)
1.76	974	U00968	SREBF1	sterol regulatory element binding transcription factor 1
1.47	1924	H64807		placental folate transporter (H. sapiens)
1.44	1873	L07648	MXI1	MAX interacting protein 1
1.41	350	D26129	RNASE1	ribonuclease, RNase A family, 1 (pancreatic)
1.38	377	Z50753	GUCA2B	guanylate cyclase activator 2B (uroguanylin)
1.21	1757	H16096	PMPCB	peptidase (mitochondrial processing) beta
1.01	765	M76378	CSRP1	cysteine and glycine-rich protein 1
0.86	1346	T62947	RPL24	ribosomal protein L24
0.84	1976	K03474	AMH	anti-Mullerian hormone
0.75	792	R88740	ATP5J	ATP synthase, H+ transporting, mitochondrial F0 complex, subunit F6
0.74	70	T61661	PFN1	profilin 1
0.74	554	H24401		MAP kinase phosphatase-1 (H. sapiens)
0.74	698	T51261	SERPINE2	serine (or cysteine) proteinase inhibitor, clade E (nexin), member 2
0.72	1546	T51493	PPP2R5C	protein phosphatase 2, regulatory subunit B (B56), gamma isoform
0.64	1740	M81651	SEMG2	semenogelin II
0.50	1641	K02268	PDYN	prodynorphin
0.42	1024	R65697	REL	v-rel reticuloendotheliosis viral oncogene homolog (avian)
0.37	1644	R80427		C4-dicarboxylate transport sensor protein DCTB (R. leguminosarum)
0.32	1623	T94993	FGFR2	fibroblast growth factor receptor 2 (keratinocyte growth factor receptor)
0.14	1909	U10886	PTPRJ	protein tyrosine phosphatase, receptor type, J
0.12	1482	T64012	CHRND	cholinergic receptor, nicotinic, delta polypeptide
0.10	1094	R33481	ATF7	activating transcription factor 7
0.06	187	T51023	HSPCB	heat shock 90kDa protein 1, beta
0.06	1504	H78386	IL1R2	interleukin 1 receptor, type II
0.03	1241	T64885		general negative regulator of transcription subunit 1 (S. cerevisiae)

TABLE 3. MOST IMPORTANT GENES FOR DISTINGUISHING COLON TUMORS, AS SELECTED BY THE JCFO

well. We occasionally tested quadratic kernels for completeness but our results are consistent with earlier work: a linear kernel is very effective. For the RVM, logistic regression, and sparse probit regression, we also tested a nonkernelized hyperplane classifier directly in the feature space; this is not possible for the SVM.

Since the JCFO has been designed to identify the optimal genes as well as the optimal classifier, we further analyzed the genes that are identified as most important by the classifier. Tables 2 and 3 show the genes identified by the JCFO as being most important for making a diagnostic decision. The reported values of θ in these tables were obtained by taking the mean of the θ obtained for each of the classifiers designed in the LOOCV (so N = 72 in Table 2 and N = 62 in Table 3).

We also examined three different breast cancer datasets. The first was a Duke University study in which N = 38 breast tumors were classified based on estrogen receptor (ER) status. The second was a Duke University study in which the same N = 38 breast tumors were classified based on lymph node (LN) involvement status. The third was a set of N = 58 breast tissues collected by researchers at Lund University in Sweden. To accelerate the time required to complete the full LOOCV for all of the methods and to give as much performance benefit as possible to the classification methods that suffer from the curse of dimensionality, the three breast cancer datasets were pared in advance to include only the 2,000 most relevant genes as determined by the Fisher discriminant ratio (FDR). Restricting the set of available genes in this way does not improve the accuracy of the JCFO because it is designed to perform feature selection as part of its optimization, but the smaller set of relevant initial features does improve the accuracy of the other methods.

In Table 4, we present a full leave-one-out cross-validation study for each of the three datasets to compare the accuracy of the diagnostic classification reported by the JCFO against that reported by the SVM, the RVM, and sparse probit regression. Since linear kernels seemed to outperform quadratic kernels in the previous tests on gene expression data (see Table 1), we do not consider quadratic kernels here.

Classifier	Duke ER status	Duke LN status	Lund
SVM (linear kernel)	97.4	78.9	87.9
RVM (linear kernel)	94.7	92.1	88.5
RVM (no kernel)	89.5	81.6	96.5
Sparse probit regression (linear kernel)	97.4	89.5	86.2
Sparse probit regression (no kernel)	84.2	89.5	96.5
JCFO (linear kernel)	97.4	94.7	98.3

TABLE 4. ACCURACY OF DIAGNOSTIC CLASSIFICATION: MULTIPLE CLASSIFIERS APPLIED TO THREE BREAST CANCER DATASETS (% CORRECT IN LOOCV STUDY)

5. DISCUSSION

First, as indicated in Tables 1 and 4, on all five datasets, the classification accuracy of the JCFO is superior to all of the other classification methods we tested or found in the literature, including the sparse probit regression EM algorithm with a Jeffreys prior as proposed by Figueiredo and Jain. Specifically, the Jeffreys EM algorithm failed to consistently learn effective classifiers when using a second-order polynomial kernel. Though the use of the Laplacian prior did permit the design of a reasonable classifier, the real benefits of nonlinear classifier design are impossible to achieve with a poorly designed polynomial kernel that is required to weight all the features as equally relevant in measuring similarity between two sets of expression profiles of genes. The JCFO improves classification performance by finding the appropriate scaling and selection of genes to use, all as part of the algorithm. Of course, this joint optimization comes at a price: the algorithm is significantly slower than the sparse probit regression algorithm of Figueiredo and Jain, though it was still acceptable for our purposes. However, the computational complexity of our algorithm might render it impractical with current technology if it were applied to datasets with several hundreds or thousands of samples. Fortunately, the sample sizes available in current datasets are typically much smaller. The large number of genes does not pose a problem since we can preprocess all the genes found useful by the sparse probit regression algorithm and use our algorithm only on this reduced set of around fifty genes as discussed above. In this case, our algorithm converges in less than half an hour.

Second, the genes that the JCFO algorithm associates with high θ values for each of these cancer types are shown in Tables 2 and 3. We note that almost all genes with high values of θ in Table 2 are of known relevance to the AML/ALL distinction. In particular, CST3, CD33, DF, HOXA9, LTC4S, PRG1, CTSD, and EPB72 were all determined by Golub *et al.*, to be predictive of AML. In addition, MPO (not identified by Golub *et al.*) is known to occur in virtually all cells of the myeloid lineage and none of the lymphoid lineage, and antibodies to MPO are used as clinical determinants of AML. CD33 is similarly a marker for AML, expressed in nearly all malignant myeloblasts. HOXA9 is transformed in myeloid cells and can lead to leukemia in animal models. DF (adipsin) is expressed during myeloid cell differentiation. Many other genes with high θ are known to play a role in myeloid/lymphoid differentiation, and a few novel genes have been identified as well. Similar results hold in the case of the colon tumor data. The genes with high values of θ in Table 3 are in many cases also known to be implicated in colon cancer or other cancers, including CDC42, MXI1, RNASE1, GUCA2B, REL, FGFR2, and PTPRJ. A few anomalous genes like AMH and SEMG2 are also given nonzero values of θ , and we are currently investigating these genes for novel properties.

Third, if the RVM and sparse probit regression are formulated without a kernel (operating directly on the feature space), they too can identify a set of diagnostically most informative genes, just like the JCFO. The difference is in the number of genes that are identified by these methods. Indeed, the JCFO typically identifies less than half as many genes as other methods while providing better diagnoses. All the methods can identify a small subset of genes (typically 50 or so) that carry complete diagnostic information, but the JCFO is more sparse than the others used here. This depends to some extent on the parameters characterizing the prior, but for comparison, we retained the priors of the RVM in the same form as used by Li *et al.* (2002) with a = b = 0. If we use other parameters, then we get better accuracy but worse feature selection (in that we lose much of the sparsity).

Finally, it is worth noting that the expression levels of many genes are well-correlated with the class variable *y* but the methods considered in this paper select only a subset of genes that carry distinct information. This is not to imply that other genes are not well correlated, but simply that if we have the information provided by the set of genes identified here, then we do not obtain new information from other genes. We are interested in identifying such genes because we believe they provide us important clues about the genetic mechanisms underlying the disease; further study and analysis of a small set of about 20 genes will be much more tractable in terms of computational and human resources than analyzing tens of thousands of genes.

In conclusion, the JCFO has successfully achieved both of its objectives: LOOCV classification accuracy above the state-of-the-art and automatic gene selection. Nevertheless, considerable scope for improvement remains, and we must still address several questions. Is our prior optimal? Does our EM formulation converge to a global maximum, or do we face multiple local maxima? Can we improve the computational efficiency of our optimization implementation? We are investigating different ways to address these issues in our current work. All code developed as part of this research is available from the first author.

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