## Statistical learning on graphs

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## Outline

(9) Statistical learning with positive definite kernels
(2) Kernels on graphs

- Motivation
- Graph distance and p.d. kernels
- Construction by regularization
- The diffusion kernel
- Harmonic analysis on graphs
- Applications


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## Part 1

# Statistical Learning with Positive Definite Kernels 

## Positive Definite (p.d.) Kernels

## Definition

A positive definite (p.d.) kernel on the set $\mathcal{X}$ is a function $K: \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ symmetric:

$$
\forall\left(\mathbf{x}, \mathbf{x}^{\prime}\right) \in \mathcal{X}^{2}, \quad K\left(\mathbf{x}, \mathbf{x}^{\prime}\right)=K\left(\mathbf{x}^{\prime}, \mathbf{x}\right)
$$

and which satisfies, for all $N \in \mathbb{N},\left(\mathbf{x}_{1}, \mathbf{x}_{2}, \ldots, \mathbf{x}_{N}\right) \in \mathcal{X}^{N}$ et $\left(a_{1}, a_{2}, \ldots, a_{N}\right) \in \mathbb{R}^{N}$ :

$$
\sum_{i=1}^{N} \sum_{j=1}^{N} a_{i} a_{j} K\left(\mathbf{x}_{i}, \mathbf{x}_{j}\right) \geq 0
$$

## Examples

## Kernels for vectors

Classical kernels for vectors ( $\mathcal{X}=\mathbb{R}^{p}$ ) include:

- The linear kernel

$$
K_{\text {lin }}\left(\mathbf{x}, \mathbf{x}^{\prime}\right)=\mathbf{x}^{\top} \mathbf{x}^{\prime} .
$$

- The polynomial kernel

- The Gaussian RBF kernel:



## Examples

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- The polynomial kernel

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K_{\text {poly }}\left(\mathbf{x}, \mathbf{x}^{\prime}\right)=\left(\mathbf{x}^{\top} \mathbf{x}^{\prime}+a\right)^{d} .
$$

- The Gaussian RBF kernel:



## Examples

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- The polynomial kernel

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$$

- The Gaussian RBF kernel:

$$
K_{\text {Gaussian }}\left(\mathbf{x}, \mathbf{x}^{\prime}\right)=\exp \left(-\frac{\left\|\mathbf{x}-\mathbf{x}^{\prime}\right\|^{2}}{2 \sigma^{2}}\right) .
$$

## P.d. kernels are inner products

## Theorem (Aronszajn, 1950)

$K$ is a p.d. kernel on the set $\mathcal{X}$ if and only if there exists a Hilbert space $\mathcal{H}$ and a mapping

$$
\Phi: \mathcal{X} \mapsto \mathcal{H},
$$

such that, for any $\mathbf{x}, \mathbf{x}^{\prime}$ in $\mathcal{X}$ :

$$
K\left(\mathbf{x}, \mathbf{x}^{\prime}\right)=\left\langle\Phi(\mathbf{x}), \Phi\left(\mathbf{x}^{\prime}\right)\right\rangle_{\mathcal{H}} .
$$



## Reproducing kernel Hilbert space

## Definition

Let $\mathcal{X}$ be a set and $\mathcal{H} \subset \mathbb{R}^{\mathcal{X}}$ be a class of functions forming a (real) Hilbert space with inner product $\langle., .\rangle_{\mathcal{H}}$. The function $K: \mathcal{X}^{2} \mapsto \mathbb{R}$ is called a reproducing kernel (r.k.) of $\mathcal{H}$ if
(1) $\mathcal{H}$ contains all functions of the form

$$
\forall \mathbf{x} \in \mathcal{X}, \quad K_{\mathbf{x}}: \mathbf{t} \mapsto K(\mathbf{x}, \mathbf{t}) .
$$

(2) For every $\mathbf{x} \in \mathcal{X}$ and $f \in \mathcal{H}$ the reproducing property holds:

$$
f(\mathbf{x})=\left\langle f, K_{\mathbf{x}}\right\rangle_{\mathcal{H}} .
$$

If a r.k. exists, then $\mathcal{H}$ is called a reproducing kernel Hilbert space (RKHS).

## Positive definite and reproducing kernels are the same

## Theorem (Aronszajn, 1950)

$K$ is a p.d. kernel if and only if there exists a RKHS having $K$ as r.k.

## Explicit construction of the RKHS

- If $K$ is p.d., then the RKHS $\mathcal{H}$ is the vector subspace of $\mathbb{R}^{\mathcal{X}}$ spanned by the functions $\left\{K_{x}\right\}_{x \in \mathcal{X}}$ (and their pointwise limits)
- For any $f, g \in \mathcal{H}_{0}$, given by:

the inner product is given by:


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- For any $f, g \in \mathcal{H}_{0}$, given by:

$$
f=\sum_{i} a_{i} K_{\mathbf{x}_{i}}, \quad g=\sum_{j} b_{j} K_{\mathbf{y}_{j}},
$$

the inner product is given by:

$$
\langle f, g\rangle_{\mathcal{H}_{0}}:=\sum_{i, j} a_{i} b_{j} K\left(\mathbf{x}_{i}, \mathbf{y}_{j}\right), \quad\|f\|_{\mathcal{H}_{0}}^{2}=\sum_{i, j} a_{i} a_{j} K\left(\mathbf{x}_{i}, \mathbf{x}_{j}\right) .
$$

## Example : RKHS of the linear kernel

$$
\begin{cases}K\left(\mathbf{x}, \mathbf{x}^{\prime}\right) & =\mathbf{x}^{\top} \mathbf{x}^{\prime} \\ f(\mathbf{x}) & =w^{\top} \mathbf{x} \\ \|f\|_{\mathcal{H}} & =\|w\|_{2}\end{cases}
$$



## Smoothness functional

A simple inequality

- By Cauchy-Schwarz we have, for any function $f \in \mathcal{H}$ and any two points $\mathbf{x}, \mathbf{x}^{\prime} \in \mathcal{X}$ :

$$
\begin{aligned}
f(\mathbf{x})-f\left(\mathbf{x}^{\prime}\right) \mid & =\left|\left\langle f, K_{\mathbf{x}}-K_{\mathbf{x}^{\prime}}\right\rangle_{\mathcal{H}}\right| \\
& \leq\|f\|_{\mathcal{H}} \times\left\|K_{\mathbf{x}}-K_{\mathbf{x}^{\prime}}\right\|_{\mathcal{H}} \\
& =\|f\|_{\mathcal{H}} \times d_{K}\left(\mathbf{x}, \mathbf{x}^{\prime}\right) .
\end{aligned}
$$

- The norm of a function in the RKHS controls how fast the function varies over $\mathcal{X}$ with respect to the geometry defined by the kernel (Lipschitz with constant $\|f\|_{\mathcal{H}}$ ).


## Important message

## Small norm $\Longrightarrow$ slow variations.

## A useful property

## Representer theorem (Kimeldorf and Wahba, 1971)

- Let $\mathcal{X}$ be a set endowed with a p.d. kernel $K, \mathcal{H}_{K}$ the corresponding RKHS, and $\mathcal{S}=\left\{\mathbf{x}_{1}, \cdots, \mathbf{x}_{n}\right\} \subset \mathcal{X}$ a finite set of points in $\mathcal{X}$.
- Let $\psi: \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ be a function of $n+1$ variables, strictly increasing with respect to the last variable.
- Then, any solution to the optimization problem:

$$
\min _{f \in \mathcal{H}_{K}} \Psi\left(f\left(\mathbf{x}_{1}\right), \cdots, f\left(\mathbf{x}_{n}\right),\|f\|_{\mathcal{H}_{K}}\right)
$$

admits a representation of the form:

$$
\forall \mathbf{x} \in \mathcal{X}, \quad f(\mathbf{x})=\sum_{i=1}^{n} \alpha_{i} K\left(\mathbf{x}_{i}, \mathbf{x}\right) .
$$

## Learning from data

## General setting

- Observation: $\left\{z_{1}, \ldots, z_{n}\right\}$ where $z_{i}=\left(\mathbf{x}_{i}, y_{i}\right) \in \mathcal{X} \times \mathcal{Y}$
- Goal: learn a function $f: \mathcal{X} \rightarrow \mathbb{R}$
- Examples: density estimation, pattern recognition, regression, outlier detection, clustering, compression, low-dimensional embedding...


## Learning from data

## Empirical risk minimization (ERM)

(1) Define a loss function $l(f, z)$ and a space of functions $\mathcal{F}$.
(2) Minimize the empirical average loss over $\mathcal{F}$ :

$$
\hat{f} \in \underset{f \in \mathcal{F}}{\arg \min } \frac{1}{n} \sum_{i=1}^{n} l\left(f, z_{i}\right) .
$$

## General properties of ERM

- If $\mathcal{F}$ is not "too large" then the ERM is consistent ( $\hat{f}$ is close to the best possible $f \in \mathcal{F}$ as the number of observations increases).
- If $\mathcal{F}$ is not "too small" then the best possible $f \in \mathcal{F}$ is a "good" solution.
- Challenge: choose a "small" F that contains "good" functions.


## Learning from data

## Empirical risk minimization (ERM)

(1) Define a loss function $I(f, z)$ and a space of functions $\mathcal{F}$.
(2) Minimize the empirical average loss over $\mathcal{F}$ :

$$
\hat{f} \in \underset{f \in \mathcal{F}}{\arg \min } \frac{1}{n} \sum_{i=1}^{n} I\left(f, z_{i}\right) .
$$

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- Challenge: choose a "small" $\mathcal{F}$ that contains "good" functions.


## Learning with kernels

## ERM in RKHS

- Take $\mathcal{F}$ to be a ball in the RKHS:

$$
\mathcal{F}_{B}=\left\{f \in \mathcal{H}:\|f\|_{\mathcal{H}} \leq B\right\} .
$$

- Advantage: by controlling the "size" of $\mathcal{F}$ (related to $B$ ) the ERM principle works (consistency and theoretical rates of convergence).
- The kernel should be chosen s.t. some "good" functions have a small RKHS norm.


## Example: pattern recognition



APPLE



- Input variables $\mathbf{x} \in \mathcal{X}$
- Output $y \in\{-1,1\}$.
- Training set $\mathcal{S}=\left\{\left(\mathbf{x}_{1}, y_{1}\right), \ldots,\left(\mathbf{x}_{n}, y_{n}\right)\right\}$.


## Large-margin classifiers

## General setting

- For pattern recognition $\mathcal{Y}=\{-1,1\}$.
- Goal: estimate a function $f: \mathcal{X} \rightarrow \mathbb{R}$ to predict $\mathbf{y}$ from the sign of $f(\mathbf{x})$
- The margin for a pair $(\mathbf{x}, \mathbf{y})$ is $\mathbf{y} f(\mathbf{x})$.
- Focusing on large margins ensures that $f(\mathbf{x})$ has the same sign as $\mathbf{y}$ and a large absolute value (confidence).
- Leads to a loss function

$$
I(f,(\mathbf{x}, \mathbf{y}))=\phi(\mathbf{y} f(\mathbf{x}))
$$

where $\phi: \mathbb{R} \rightarrow \mathbb{R}$ is non-increasing.

## ERM in for large-margin classifiers: Theory

## Theoretical results

- The ERM estimator $\hat{f}_{n}$ solves:

$$
\left\{\begin{array}{l}
\min _{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^{n} \phi\left(\mathbf{y}_{i} f\left(\mathbf{x}_{i}\right)\right) \\
\text { subject to }\|f\|_{\mathcal{H}} \leq B .
\end{array}\right.
$$

- Let $P$ an unknown distribution over $\mathcal{X} \times \mathcal{Y}$, assume $\mathcal{S}=\left(\mathbf{x}_{i}, y_{i}\right)_{i=1, \ldots, n}$ i.i.d. according to $P$.
- Assume $K$ upper bounded by $\kappa$ and $\phi$ Lipschitz with constant $L_{\phi}$.
- For the $\phi$-risk $R_{\phi}(f)=\mathrm{E} \phi(Y f(X))$ we have:

$$
\mathbf{E} R_{\phi}\left(\hat{t}_{n}\right) \leq \inf _{f \in \mathcal{F}_{B}} R_{\phi}(f)+\frac{8 L_{\phi} \kappa B}{\sqrt{n}} .
$$

## ERM in for large-margin classifiers: Practice

## Reformulation as penalized minimization

- We must solve the constrained minimization problem:

$$
\left\{\begin{array}{l}
\min _{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^{n} \phi\left(\mathbf{y}_{i} f\left(\mathbf{x}_{i}\right)\right) \\
\text { subject to }\|f\|_{\mathcal{H}} \leq B
\end{array}\right.
$$

- To make this practical we assume that $\phi$ is convex.
- The problem is then a convex problem in $f$ for which strong duality holds. In particular $f$ solves the problem if and only if it solves for some dual parameter $\lambda$ the unconstrained problem:

$$
\min _{f \in \mathcal{H}}\left\{\frac{1}{n} \sum_{i=1}^{n} \phi\left(\mathbf{y}_{i} f\left(\mathbf{x}_{i}\right)\right)+\lambda\|f\|_{\mathcal{H}}^{2}\right\}
$$

and complimentary slackness holds $\left(\lambda=0\right.$ or $\left.\|f\|_{\mathcal{H}}=B\right)$.

## Optimization in RKHS

- By the representer theorem, the solution of the unconstrained problem can be expanded as:

$$
f(\mathbf{x})=\sum_{i=1}^{n} \alpha_{i} K\left(\mathbf{x}_{i}, \mathbf{x}\right)
$$

- Plugging into the original problem we obtain the following unconstrained and convex optimization problem in $\mathbb{R}^{n}$ :

$$
\min _{\alpha \in \mathbb{R}^{n}}\left\{\frac{1}{n} \sum_{i=1}^{n} \phi\left(\mathbf{y}_{i} \sum_{j=1}^{n} \alpha_{j} K\left(\mathbf{x}_{i}, \mathbf{x}_{j}\right)\right)+\lambda \sum_{i, j=1}^{n} \alpha_{i} \alpha_{j} K\left(\mathbf{x}_{i}, \mathbf{x}_{j}\right)\right\}
$$

- This can be implemented using general packages for convex optimization or specific algorithms (e.g., for SVM).


## Loss function examples



| Method | $\phi(u)$ |
| :---: | :---: |
| Kernel logistic regression | $\log \left(1+e^{-u}\right)$ |
| Support vector machine (1-SVM) | $\max (1-u, 0)$ |
| Support vector machine (2-SVM) | $\max (1-u, 0)^{2}$ |
| Boosting | $e^{-u}$ |

## Kernel methods: Summary

- 3 ways to map $\mathcal{X}$ to a Hilbert space:
(1) Explicitly define and compute $\Phi: \mathcal{X} \rightarrow \mathcal{H}$
(2) Define a p.d. kernel over $\mathcal{X}$
(3) Define a RKHS over $\mathcal{X}$
- The kernel trick allows to extend many linear algorithms to non-linear settings and to general data (even non-vectorial).
- The norm in the RKHS can be used as regularization for empirical risk minimization. This is theoretically justified and leads to efficient algorithms (often finite-dimensional convex problem thanks to the representer theorem).
- We are now ready to learn with graphs by defining positive definite kernels for graphs!


## Part 2

## Kernels on Graphs

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- Graph distance and p.d. kernels
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## Example: web



## Example: social network



## Example: protein-protein interaction



## Kernel on a graph



- We need a kernel $K\left(\mathbf{x}, \mathbf{x}^{\prime}\right)$ between nodes of the graph.
- Example: predict gene protein functions from high-throughput protein-protein interaction data.


## General remarks

## Strategies to make a kernel on a graph

- $\mathcal{X}$ being finite, any symmetric semi-definite matrix $K$ defines a valid p.d. kernel on $\mathcal{X}$.
- How to "translate" the graph topology into the kernel?
- Direct geometric approach: $K_{i, j}$ should be "large" when $\mathbf{x}_{i}$ and $\mathbf{x}_{j}$ are "close" to each other on the graph?
- Functional approach: "If I"k should be "smat"" when I is "smooth" on the graph?
- Link discrete/continuous: is there an equivalent to the continuous Gaussien kernel on the graph (e.g., limit by fine discretization)?


## General remarks

## Strategies to make a kernel on a graph

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- Direct geometric approach: $K_{i, j}$ should be "large" when $\mathbf{x}_{i}$ and $\mathbf{x}_{j}$ are "close" to each other on the graph?
- Functional approach: $\|f\|_{K}$ should be "small" when $f$ is "smooth" on the graph?
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## Conditionally p.d. kernels

## Hilbert distance

- Any p.d. kernels is an inner product in a Hilbert space

$$
K\left(\mathbf{x}, \mathbf{x}^{\prime}\right)=\left\langle\Phi(\mathbf{x}), \Phi\left(\mathbf{x}^{\prime}\right)\right\rangle_{\mathcal{H}}
$$

- It defines a Hilbert distance:

$$
d_{K}\left(\mathbf{x}, \mathbf{x}^{\prime}\right)^{2}=K(\mathbf{x}, \mathbf{x})+K\left(\mathbf{x}^{\prime}, \mathbf{x}^{\prime}\right)-2 K\left(\mathbf{x}, \mathbf{x}^{\prime}\right)
$$

- $-d_{K}^{2}$ is conditionally positive definite, i.e.:

$$
\forall t>0, \quad \exp \left(-t d_{K}\left(\mathbf{x}, \mathbf{x}^{\prime}\right)^{2}\right) \text { is p.d. }
$$

## Graph distance

## Graph embedding in a Hilbert space

- Given a graph $G=(V, E)$, the graph distance $d_{G}\left(x, x^{\prime}\right)$ between any two vertices is the length of the shortest path between $x$ and $x^{\prime}$.
- We say that the graph $G=(V, E)$ can be embedded (exactly) in a Hilbert space if $-d_{G}$ is c.p.d., which implies in particular that $\exp \left(-t d_{G}\left(x, x^{\prime}\right)\right)$ is p.d. for all $t>0$.


## emma

- In general graphs can not be embedded exactly in Hilbert spaces.
- In some cases exact embeddings exists, e.g.
- trees can be embedded exactly,
- closed chains can be embedded exactly.


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## Lemma

- In general graphs can not be embedded exactly in Hilbert spaces.
- In some cases exact embeddings exists, e.g.:
- trees can be embedded exactly,
- closed chains can be embedded exactly.


## Example: non-c.p.d. graph distance



## Graph distance on trees are c.p.d.

## Proof

- Let $G=(V, E)$ a tree
- Fix a root $x_{0} \in V$
- Represent any vertex $x \in V$ by a vector $\Phi(x) \in \mathbb{R}^{|E|}$, where $\Phi(x)_{i}=1$ is the $i$-th edge is in the (unique) path between $x$ and $x_{0}, 0$ otherwise.
- Then:

$$
d_{G}\left(x, x^{\prime}\right)=\left\|\Phi(x)-\Phi\left(x^{\prime}\right)\right\|^{2}
$$

and therefore $-d_{G}$ is c.p.d., in particular $\exp \left(-t d_{G}\left(x, x^{\prime}\right)\right)$ is p.d. for all $t>0$.

## Example

$$
\left[e^{-d_{G}(i, j)}\right]=\left(\begin{array}{rrrrr}
1 & 0.14 & 0.37 & 0.14 & 0.05 \\
0.14 & 1 & 0.37 & 0.14 & 0.05 \\
0.37 & 0.37 & 1 & 0.37 & 0.14 \\
0.14 & 0.14 & 0.37 & 1 & 0.37 \\
0.05 & 0.05 & 0.14 & 0.37 & 1
\end{array}\right)
$$

## Graph distance on closed chains are c.p.d.

## Proof: case $|V|=2 p$

- Let $G=(V, E)$ a cycle with an even number of vertices $|V|=2 p$
- Fix a root $x_{0} \in V$, number the $2 p$ edges from $x_{0}$ to $x_{0}$.
- Map the $2 p$ edges in $\mathbb{R}^{p}$ to $\left(e_{1}, \ldots, e_{p},-e_{1}, \ldots,-e_{p}\right)$
- Map a vertex $v$ to the sum of the edges in the shortest path between $x_{0}$ and $v$.



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## Functional approach

## Motivation

- How to make p.d. kernel on general graphs?
- Making a kernel is equivalent to defining a RKHS.
- There are intuitive notions of smoothness on a graph


## Idea

- Define a priori a smoothness functional on the functions $f: \mathcal{X} \rightarrow \mathbb{R}$.
- Show that it defines a RKHS and identify the corresponding kernel


## Notations

$$
A=\left(\begin{array}{lllll}
0 & 0 & 1 & 0 & 0 \\
0 & 0 & 1 & 0 & 0 \\
1 & 1 & 0 & 1 & 0 \\
0 & 0 & 1 & 0 & 1 \\
0 & 0 & 0 & 1 & 0
\end{array}\right), \quad D=\left(\begin{array}{lllll}
1 & 0 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 & 0 \\
0 & 0 & 3 & 0 & 0 \\
0 & 0 & 0 & 2 & 0 \\
0 & 0 & 0 & 0 & 1
\end{array}\right)
$$

## Graph Laplacian

## Definition

The Laplacian of the graph is the matrix $L=D-A$.

$$
L=D-A=\left(\begin{array}{ccccc}
1 & 0 & -1 & 0 & 0 \\
0 & 1 & -1 & 0 & 0 \\
-1 & -1 & 3 & -1 & 0 \\
0 & 0 & -1 & 2 & -1 \\
0 & 0 & 0 & -1 & 1
\end{array}\right)
$$

## Properties of the Laplacian

## Lemma

Let $L=D-A$ be the Laplacian of a connected graph:

- For any $f: \mathcal{X} \rightarrow \mathbb{R}$,

$$
\Omega(f):=\sum_{i \sim j}\left(f\left(\mathbf{x}_{i}\right)-f\left(\mathbf{x}_{j}\right)\right)^{2}=f^{\top} L f
$$

- L is a symmetric positive semi-definite matrix
- 0 is an eigenvalue with multiplicity 1 associated to the constant eigenvector $1=(1, \ldots, 1)$
- The image of $L$ is

$$
\operatorname{Im}(L)=\left\{f \in \mathbb{R}^{m}: \sum_{i=1}^{m} f_{i}=0\right\}
$$

## Proof: link between $\Omega(f)$ and $L$

$$
\begin{aligned}
\Omega(f) & =\sum_{i \sim j}\left(f\left(\mathbf{x}_{i}\right)-f\left(\mathbf{x}_{j}\right)\right)^{2} \\
& =\sum_{i \sim j}\left(f\left(\mathbf{x}_{i}\right)^{2}+f\left(\mathbf{x}_{j}\right)^{2}-2 f\left(\mathbf{x}_{i}\right) f\left(\mathbf{x}_{j}\right)\right) \\
& =\sum_{i=1}^{m} D_{i, i} f\left(\mathbf{x}_{i}\right)^{2}-2 \sum_{i \sim j} f\left(\mathbf{x}_{i}\right) f\left(\mathbf{x}_{j}\right) \\
& =f^{\top} D f-f^{\top} A f \\
& =f^{\top} L f
\end{aligned}
$$

## Proof: eigenstructure of $L$

- $L$ is symmetric because $A$ and $D$ are symmetric.
- For any $f \in \mathbb{R}^{m}, f^{\top} L f=\Omega(f) \geq 0$, therefore the (real-valued) eigenvalues of $L$ are $\geq 0: L$ is therefore positive semi-definite.
- $f$ is an eigenvector associated to eigenvalue 0
iff $f^{\top} L f=0$
iff $\sum_{i \sim j}\left(f\left(\mathbf{x}_{i}\right)-f\left(\mathbf{x}_{j}\right)\right)^{2}=0$,
iff $f\left(\mathbf{x}_{i}\right)=f\left(\mathbf{x}_{j}\right)$ when $i \sim j$,
iff $f$ is constant (because the graph is connected).
- $L$ being symmetric, $\operatorname{Im}(L)$ is the orthogonal supplement of $\operatorname{Ker}(L)$, that is, the set of functions orthogonal to 1.


## Our first graph kernel

## Theorem

The set $\mathcal{H}=\left\{f \in \mathbb{R}^{m}: \sum_{i=1}^{m} f_{i}=0\right\}$ endowed with the norm:

$$
\Omega(f)=\sum_{i \sim j}\left(f\left(\mathbf{x}_{i}\right)-f\left(\mathbf{x}_{j}\right)\right)^{2}
$$

is a RKHS whose reproducing kernel is $L^{*}$, the pseudo-inverse of the graph Laplacian.

## Proof (1/2)

- Resticted to $\mathcal{H}$, the symmetric bilinear form:

$$
\langle f, g\rangle=f^{\top} L g
$$

is positive definite (because $L$ is positive semi-definite, and $\mathcal{H}=\operatorname{Im}(L))$. It is therefore a scalar product, making of $\mathcal{H}$ a Hilbert space (in fact Euclidean).

- The norm in this Hilbert space $\mathcal{H}$ is:

$$
\|f\|^{2}=\langle f, f\rangle=f^{\top} L f=\Omega(f)
$$

## Proof (2/2)

To check that $\mathcal{H}$ is a RKHS with reproducing kernel $K=L^{*}$, it suffices to show that:

$$
\begin{cases}\forall \mathbf{x} \in \mathcal{X}, & K_{\mathbf{x}} \in \mathcal{H}, \\ \forall(\mathbf{x}, f) \in \mathcal{X} \times \mathcal{H}, & \left\langle f, K_{\mathbf{x}}\right\rangle=f(\mathbf{x}) .\end{cases}
$$

- $\operatorname{Ker}(K)=\operatorname{Ker}\left(L^{*}\right)=\operatorname{Ker}(L)$, implying $K \mathbf{1}=0$. Therefore, each row/column of $K$ is in $\mathcal{H}$.
- For any $f \in \mathcal{H}$, if we note $g_{i}=\langle K(i, \cdot), f\rangle$ we get:

$$
g=K L f=L^{*} L f=\Pi_{\mathcal{H}}(f)=f .
$$

As a conclusion $K=L^{*}$ is the reproducing kernel of $\mathcal{H}$.

## Example

$$
L^{*}=\left(\begin{array}{rrrrr}
0.88 & -0.12 & 0.08 & -0.32 & -0.52 \\
-0.12 & 0.88 & 0.08 & -0.32 & -0.52 \\
0.08 & 0.08 & 0.28 & -0.12 & -0.32 \\
-0.32 & -0.32 & -0.12 & 0.48 & 0.28 \\
-0.52 & -0.52 & -0.32 & 0.28 & 1.08
\end{array}\right)
$$

## Outline

(1) Statistical learning with positive definite kernels
(2) Kernels on graphs

- Motivation
- Graph distance and p.d. kernels
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## The diffusion equation

## Lemma

For any $\mathbf{x}_{0} \in \mathbb{R}^{d}$, the function:

$$
K_{\mathbf{x}_{0}}(\mathbf{x}, t)=K_{t}\left(\mathbf{x}_{0}, \mathbf{x}\right)=\frac{1}{(4 \pi t)^{\frac{d}{2}}} \exp \left(-\frac{\left\|\mathbf{x}-\mathbf{x}_{0}\right\|^{2}}{4 t}\right)
$$

is solution of the diffusion equation:

$$
\frac{\partial}{\partial t} K_{\mathbf{x}_{0}}(\mathbf{x}, t)=\Delta K_{\mathbf{x}_{0}}(\mathbf{x}, t)
$$

with initial condition $K_{\mathbf{x}_{0}}(\mathbf{x}, 0)=\delta_{\mathbf{x}_{0}}(\mathbf{x})$.

## Discrete diffusion equation

- For finite-dimensional $f_{t} \in \mathbb{R}^{m}$, the diffusion equation becomes:

$$
\frac{\partial}{\partial t} f_{t}=-L f_{t}
$$

which admits the following solution:

$$
f_{t}=f_{0} e^{-t L}
$$

- This suggest to consider:

$$
K=e^{-t L}
$$

which is indeed symmetric positive semi-definite. We call it the diffusion kernel or heat kernel.

## Example: complete graph



## Example: closed chain



$$
K_{i, j}=\frac{1}{m} \sum_{\nu=0}^{m-1} \exp \left[-2 t\left(1-\cos \frac{2 \pi \nu}{m}\right)\right] \cos \frac{2 \pi \nu(i-j)}{m}
$$

## Example

$$
e^{-L}=\left(\begin{array}{lllll}
0.50 & 0.13 & 0.24 & 0.10 & 0.04 \\
0.13 & 0.50 & 0.24 & 0.10 & 0.04 \\
0.24 & 0.24 & 0.24 & 0.18 & 0.10 \\
0.10 & 0.10 & 0.18 & 0.32 & 0.30 \\
0.04 & 0.04 & 0.10 & 0.30 & 0.52
\end{array}\right)
$$

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## Spectrum of the diffusion kernel

- Let $0=\lambda_{1}<\lambda_{2} \leq \ldots \leq \lambda_{m}$ be the eigenvalues of the Laplacian:

$$
L=\sum_{i=1}^{m} \lambda_{i} u_{i} u_{i}^{\top} \quad\left(\lambda_{i} \geq 0\right)
$$

- The diffusion kernel $K_{t}$ is an invertible matrix because its eigenvalues are strictly positive:

$$
K_{t}=\sum_{i=1}^{m} e^{-t \lambda_{i}} u_{i} u_{i}^{\top}
$$

## Norm in the diffusion RKHS

- For any function $f \in \mathbb{R}^{m}$, let:

$$
\hat{f}_{i}=u_{i}^{\top} f
$$

be the Fourier coefficients of $f$ (projection of $f$ onto the eigenbasis of $K$ ).

- The RKHS norm of $f$ is then:

$$
\|f\|_{K_{t}}^{2}=f^{\top} K^{-1} f=\sum_{i=1}^{m} e^{t \lambda_{i}} \hat{\tilde{f}}_{i}^{2}
$$

## Generalization

This observation suggests to define a whole family of kernels:

$$
K_{r}=\sum_{i=1}^{m} r\left(\lambda_{i}\right) u_{i} u_{i}^{\top}
$$

associated with the following RKHS norms:

$$
\|f\|_{K_{r}}^{2}=\sum_{i=1}^{m} \frac{\hat{f}_{i}^{2}}{r\left(\lambda_{i}\right)}
$$

where $r: \mathbb{R}^{+} \rightarrow \mathbb{R}_{*}^{+}$is a non-increasing function.

## Example : regularized Laplacian

$$
\begin{gathered}
r(\lambda)=\frac{1}{\lambda+\epsilon}, \quad \epsilon>0 \\
K=\sum_{i=1}^{m} \frac{1}{\lambda_{i}+\epsilon} u_{i} u_{i}^{\top}=(L+\epsilon I)^{-1} \\
\|f\|_{K}^{2}=f^{\top} K^{-1} f=\sum_{i \sim j}\left(f\left(\mathbf{x}_{i}\right)-f\left(\mathbf{x}_{j}\right)\right)^{2}+\epsilon \sum_{i=1}^{m} f\left(\mathbf{x}_{i}\right)^{2} .
\end{gathered}
$$

## Example

$$
(L+I)^{-1}=\left(\begin{array}{lllll}
0.60 & 0.10 & 0.19 & 0.08 & 0.04 \\
0.10 & 0.60 & 0.19 & 0.08 & 0.04 \\
0.19 & 0.19 & 0.38 & 0.15 & 0.08 \\
0.08 & 0.08 & 0.15 & 0.46 & 0.23 \\
0.04 & 0.04 & 0.08 & 0.23 & 0.62
\end{array}\right)
$$

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## Applications 1: graph partitioning

- A classical relaxation of graph partitioning is:

$$
\min _{f \in \mathbb{R}^{X}} \sum_{i \sim j}\left(f_{i}-f_{j}\right)^{2} \quad \text { s.t. } \sum_{i} f_{i}^{2}=1
$$

- This can be rewritten

$$
\max _{f} \sum_{i} f_{i}^{2} \text { s.t. } \quad\|f\|_{\mathcal{H}} \leq 1
$$

- This is principal component analysis in the RKHS ("kernel PCA")



## Applications 2: search on a graph

- Let $x_{1}, \ldots, x_{q}$ a set of $q$ nodes (the query). How to find "similar" nodes (and rank them)?
- One solution:

$$
\min _{f}\|f\|_{\mathcal{H}} \quad \text { s.t. } \quad f\left(x_{i}\right) \geq 1 \text { for } i=1, \ldots, q .
$$



## Application 3: Semi-supervised learning



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## Application 4: Tumor classification from microarray data

## Data available

- Gene expression measures for more than 10k genes
- Measured on less than 100 samples of two (or more) different classes (e.g., different tumors)



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## Data available

- Gene expression measures for more than 10k genes
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## Goal

- Design a classifier to automatically assign a class to future samples from their expression profile
- Interpret biologically the differences between the classes


## Linear classifiers

## The approach

- Each sample is represented by a vector $x=\left(x_{1}, \ldots, x_{p}\right)$ where $p>10^{5}$ is the number of probes
- Classification: given the set of labeled sample, learn a linear decision function:

$$
f(x)=\sum_{i=1}^{p} \beta_{i} x_{i}+\beta_{0}
$$

- Interpretation: the weight $\beta_{i}$ quantifies the influence of gene $i$ for the classification


## Pitfalls

- No robust estimation procedure exist for 100 samples in $10^{5}$ dimensions!


## Prior knowledge

- We know the functions of many genes, and how they interact together.
- This can be represented as a graph of genes, where connected genes perform some action together
- Prior knowledge: constraint the weights of genes that work together to be similar
- Mathematically: constrain the norm of the weight vector in the RKHS of the diffusion kernel.


## Comparison



## Conclusion

## Conclusion

## What we saw

- Extension of machine learning algorithms to graph data through the definition of positive definite kernels for and on graphs
- A variety of solutions have been proposed, borrowing ideas from graph algorithms and spectral graph theory.
- Increasingly used in real-world applications.


## Unanswered question

- Theoretical foundations to guide the choice of kernel?
- How to design / choose / learn a kernel for a given application in practice?
- How to improve scalability of kernel methods + graph kernels to large datasets?


## Further reading

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