Statistical learning on graphs

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Seminar of probabilities, Institut Joseph Fourier, Grenoble, February 12, 2008.

Statistical learning with positive definite kernels

Kernels on graphs

- Motivation
- Graph distance and p.d. kernels
- Construction by regularization
- The diffusion kernel
- Harmonic analysis on graphs
- Applications

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Statistical Learning with Positive Definite Kernels

Definition

A positive definite (p.d.) kernel on the set \mathcal{X} is a function $\mathcal{K} : \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ symmetric:

$$orall\left(\mathbf{x},\mathbf{x}'
ight)\in\mathcal{X}^{2},\quad \mathbf{\textit{K}}\left(\mathbf{x},\mathbf{x}'
ight)=\mathbf{\textit{K}}\left(\mathbf{x}',\mathbf{x}
ight),$$

and which satisfies, for all $N \in \mathbb{N}$, $(\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N) \in \mathcal{X}^N$ et $(a_1, a_2, \dots, a_N) \in \mathbb{R}^N$:

$$\sum_{i=1}^{N}\sum_{j=1}^{N}a_{i}a_{j}K\left(\mathbf{x}_{i},\mathbf{x}_{j}\right)\geq0\,.$$

Examples

Kernels for vectors

Classical kernels for vectors ($\mathcal{X} = \mathbb{R}^{p}$) include:

• The linear kernel

$$\mathcal{K}_{\textit{lin}}\left(\mathbf{x},\mathbf{x}'
ight)=\mathbf{x}^{ op}\mathbf{x}'$$
 .

• The polynomial kernel

$$K_{\text{poly}}\left(\mathbf{x},\mathbf{x}'\right) = \left(\mathbf{x}^{ op}\mathbf{x}' + a
ight)^{d}$$
 .

• The Gaussian RBF kernel:

$$K_{Gaussian}(\mathbf{x}, \mathbf{x}') = \exp\left(-\frac{\|\mathbf{x} - \mathbf{x}'\|^2}{2\sigma^2}\right)$$

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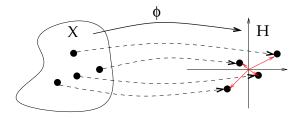
Theorem (Aronszajn, 1950)

K is a p.d. kernel on the set \mathcal{X} if and only if there exists a Hilbert space \mathcal{H} and a mapping

$$\Phi: \mathcal{X} \mapsto \mathcal{H} ,$$

such that, for any \mathbf{x}, \mathbf{x}' in \mathcal{X} :

$$K(\mathbf{x}, \mathbf{x}') = \langle \Phi(\mathbf{x}), \Phi(\mathbf{x}') \rangle_{\mathcal{H}}$$



Reproducing kernel Hilbert space

Definition

Let \mathcal{X} be a set and $\mathcal{H} \subset \mathbb{R}^{\mathcal{X}}$ be a class of functions forming a (real) Hilbert space with inner product $\langle ., . \rangle_{\mathcal{H}}$. The function $K : \mathcal{X}^2 \mapsto \mathbb{R}$ is called a reproducing kernel (r.k.) of \mathcal{H} if

H contains all functions of the form

 $\forall \mathbf{x} \in \mathcal{X}, \quad K_{\mathbf{x}} : \mathbf{t} \mapsto K(\mathbf{x}, \mathbf{t}) .$

So For every $\mathbf{x} \in \mathcal{X}$ and $f \in \mathcal{H}$ the reproducing property holds:

 $f(\mathbf{x}) = \langle f, K_{\mathbf{x}} \rangle_{\mathcal{H}}$.

If a r.k. exists, then \mathcal{H} is called a reproducing kernel Hilbert space (RKHS).

Positive definite and reproducing kernels are the same

Theorem (Aronszajn, 1950)

K is a p.d. kernel if and only if there exists a RKHS having K as r.k.

Explicit construction of the RKHS

If K is p.d., then the RKHS H is the vector subspace of ℝ^X spanned by the functions {K_x}_{x∈X} (and their pointwise limits).

• For any $f, g \in \mathcal{H}_0$, given by:

$$f = \sum_i a_i K_{\mathbf{x}_i}, \quad g = \sum_j b_j K_{\mathbf{y}_j},$$

the inner product is given by:

$$\langle f,g
angle_{\mathcal{H}_0} := \sum_{i,j} a_i b_j K\left(\mathbf{x}_i,\mathbf{y}_j
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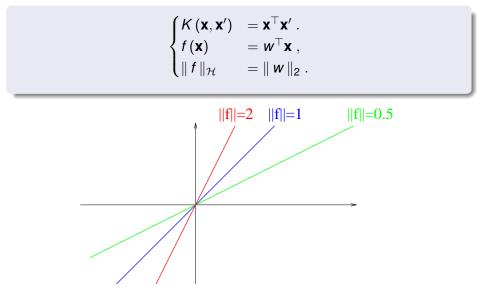
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the inner product is given by:

$$\langle f, g \rangle_{\mathcal{H}_0} := \sum_{i,j} a_i b_j \mathcal{K} \left(\mathbf{x}_i, \mathbf{y}_j \right) , \quad \| f \|_{\mathcal{H}_0}^2 = \sum_{i,j} a_i a_j \mathcal{K} \left(\mathbf{x}_i, \mathbf{x}_j \right) .$$

Example : RKHS of the linear kernel



A simple inequality

By Cauchy-Schwarz we have, for any function *f* ∈ H and any two points **x**, **x**' ∈ X:

$$\begin{aligned} \left| \begin{array}{c} f\left(\mathbf{x}\right) - f\left(\mathbf{x}'\right) \right| &= \left| \left\langle f, K_{\mathbf{x}} - K_{\mathbf{x}'} \right\rangle_{\mathcal{H}} \right| \\ &\leq \left\| \left| f \right\|_{\mathcal{H}} \times \left\| K_{\mathbf{x}} - K_{\mathbf{x}'} \right\|_{\mathcal{H}} \\ &= \left\| \left| f \right\|_{\mathcal{H}} \times d_{K} \left(\mathbf{x}, \mathbf{x}'\right) \end{aligned}$$

• The norm of a function in the RKHS controls how fast the function varies over \mathcal{X} with respect to the geometry defined by the kernel (Lipschitz with constant $|| f ||_{\mathcal{H}}$).

Important message

Small norm \implies slow variations.

A useful property

Representer theorem (Kimeldorf and Wahba, 1971)

- Let X be a set endowed with a p.d. kernel K, H_K the corresponding RKHS, and S = {x₁, · · · , x_n} ⊂ X a finite set of points in X.
- Let Ψ : ℝⁿ⁺¹ → ℝ be a function of n + 1 variables, strictly increasing with respect to the last variable.
- Then, any solution to the optimization problem:

$$\min_{f\in\mathcal{H}_{K}}\Psi\left(f\left(\mathbf{x}_{1}\right),\cdots,f\left(\mathbf{x}_{n}\right),\|f\|_{\mathcal{H}_{K}}\right),$$

admits a representation of the form:

$$\forall \mathbf{x} \in \mathcal{X}, \quad f(\mathbf{x}) = \sum_{i=1}^{n} \alpha_i K(\mathbf{x}_i, \mathbf{x}) \;.$$

General setting

- Observation: $\{z_1, \ldots, z_n\}$ where $z_i = (\mathbf{x}_i, y_i) \in \mathcal{X} \times \mathcal{Y}$
- Goal: learn a function $f : \mathcal{X} \to \mathbb{R}$
- Examples: density estimation, pattern recognition, regression, outlier detection, clustering, compression, low-dimensional embedding...

Learning from data

Empirical risk minimization (ERM)

- Define a loss function I(f, z) and a space of functions \mathcal{F} .
- Minimize the empirical average loss over F:

$$\hat{f} \in \underset{f \in \mathcal{F}}{\operatorname{arg\,min}} \frac{1}{n} \sum_{i=1}^{n} I(f, z_i).$$

General properties of ERM

- If *F* is not "too large" then the ERM is consistent (*f* is close to the best possible *f* ∈ *F* as the number of observations increases).
- If *F* is not "too small" then the best possible *f* ∈ *F* is a "good" solution.
- Challenge: choose a "small" \mathcal{F} that contains "good" functions.

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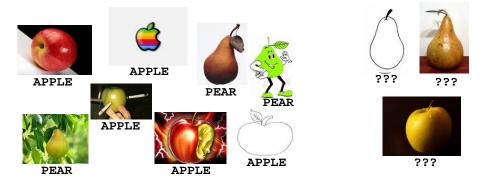
ERM in RKHS

• Take \mathcal{F} to be a ball in the RKHS:

$$\mathcal{F}_{\boldsymbol{B}} = \{f \in \mathcal{H} \, : \, \| f \|_{\mathcal{H}} \leq \boldsymbol{B}\} \; .$$

- Advantage: by controlling the "size" of \mathcal{F} (related to *B*) the ERM principle works (consistency and theoretical rates of convergence).
- The kernel should be chosen s.t. some "good" functions have a small RKHS norm.

Example: pattern recognition



- Input variables $\mathbf{x} \in \mathcal{X}$
- Output $y \in \{-1, 1\}$.
- Training set $S = \{(\mathbf{x}_1, y_1), ..., (\mathbf{x}_n, y_n)\}.$

Large-margin classifiers

General setting

- For pattern recognition $\mathcal{Y} = \{-1, 1\}$.
- Goal: estimate a function $f : \mathcal{X} \to \mathbb{R}$ to predict **y** from the sign of $f(\mathbf{x})$
- The margin for a pair (\mathbf{x}, \mathbf{y}) is $\mathbf{y}f(\mathbf{x})$.
- Focusing on large margins ensures that *f*(**x**) has the same sign as **y** and a large absolute value (confidence).
- Leads to a loss function

 $I(f,(\mathbf{x},\mathbf{y})) = \phi(\mathbf{y}f(\mathbf{x})) ,$

where $\phi : \mathbb{R} \to \mathbb{R}$ is non-increasing.

ERM in for large-margin classifiers: Theory

Theoretical results

• The ERM estimator \hat{f}_n solves:

$$\begin{cases} \min_{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^{n} \phi\left(\mathbf{y}_{i} f\left(\mathbf{x}_{i}\right)\right) \\ \text{subject to } \| f \|_{\mathcal{H}} \leq B. \end{cases}$$

- Let *P* an unknown distribution over $\mathcal{X} \times \mathcal{Y}$, assume $\mathcal{S} = (\mathbf{x}_i, y_i)_{i=1,...,n}$ i.i.d. according to *P*.
- Assume K upper bounded by κ and ϕ Lipschitz with constant L_{ϕ} .
- For the ϕ -risk $R_{\phi}(f) = \mathbf{E}\phi(Yf(X))$ we have:

$$\mathbf{E} \mathbf{R}_{\phi}\left(\hat{f}_{n}\right) \leq \inf_{f \in \mathcal{F}_{B}} \mathbf{R}_{\phi}(f) + \frac{8L_{\phi}\kappa B}{\sqrt{n}} \,.$$

ERM in for large-margin classifiers: Practice

Reformulation as penalized minimization

• We must solve the constrained minimization problem:

 $\begin{cases} \min_{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^{n} \phi\left(\mathbf{y}_{i} f\left(\mathbf{x}_{i}\right)\right) \\ \text{subject to } \| f \|_{\mathcal{H}} \leq B. \end{cases}$

- To make this practical we assume that ϕ is convex.
- The problem is then a convex problem in *f* for which strong duality holds. In particular *f* solves the problem if and only if it solves for some dual parameter λ the unconstrained problem:

$$\min_{f \in \mathcal{H}} \left\{ \frac{1}{n} \sum_{i=1}^{n} \phi\left(\mathbf{y}_{i} f\left(\mathbf{x}_{i}\right)\right) + \lambda \| f \|_{\mathcal{H}}^{2} \right\} \,,$$

and complimentary slackness holds ($\lambda = 0$ or $|| f ||_{\mathcal{H}} = B$).

Optimization in RKHS

• By the representer theorem, the solution of the unconstrained problem can be expanded as:

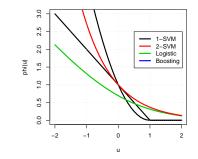
$$f(\mathbf{x}) = \sum_{i=1}^{n} \alpha_i K(\mathbf{x}_i, \mathbf{x}) \; .$$

 Plugging into the original problem we obtain the following unconstrained and convex optimization problem in ℝⁿ:

$$\min_{\boldsymbol{\alpha}\in\mathbb{R}^n}\left\{\frac{1}{n}\sum_{i=1}^n\phi\left(\mathbf{y}_i\sum_{j=1}^n\alpha_jK\left(\mathbf{x}_i,\mathbf{x}_j\right)\right)+\lambda\sum_{i,j=1}^n\alpha_i\alpha_jK\left(\mathbf{x}_i,\mathbf{x}_j\right)\right\}.$$

• This can be implemented using general packages for convex optimization or specific algorithms (e.g., for SVM).

Loss function examples



Method	$\phi(u)$
Kernel logistic regression	$\log\left(1+e^{-u}\right)$
Support vector machine (1-SVM)	$\max(1 - u, 0)$
Support vector machine (2-SVM)	$\max{(1-u,0)^2}$
Boosting	e ^{-u}

Kernel methods: Summary

• 3 ways to map \mathcal{X} to a Hilbert space:

- **1** Explicitly define and compute $\Phi : \mathcal{X} \to \mathcal{H}$
- 2 Define a p.d. kernel over \mathcal{X}
- 3 Define a RKHS over \mathcal{X}
- The kernel trick allows to extend many linear algorithms to non-linear settings and to general data (even non-vectorial).
- The norm in the RKHS can be used as regularization for empirical risk minimization. This is theoretically justified and leads to efficient algorithms (often finite-dimensional convex problem thanks to the representer theorem).
- We are now ready to learn with graphs by defining positive definite kernels for graphs!



Kernels on Graphs

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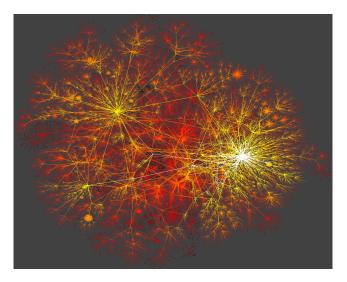
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Kernels on graphs

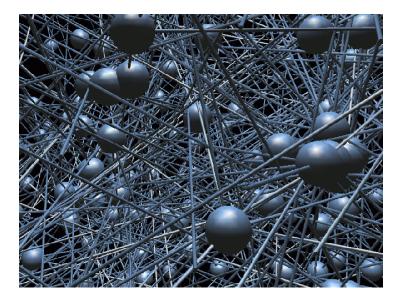
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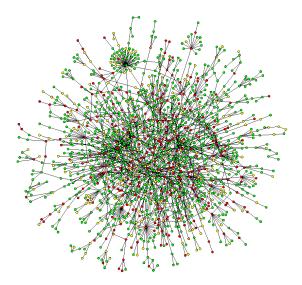
Example: web



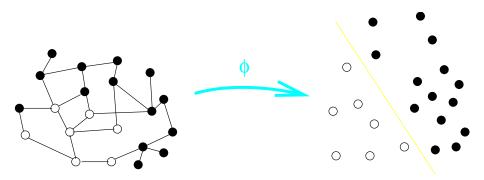
Example: social network



Example: protein-protein interaction



Kernel on a graph



- We need a kernel $K(\mathbf{x}, \mathbf{x}')$ between nodes of the graph.
- Example: predict gene protein functions from high-throughput protein-protein interaction data.

Strategies to make a kernel on a graph

• \mathcal{X} being finite, any symmetric semi-definite matrix *K* defines a valid p.d. kernel on \mathcal{X} .

How to "translate" the graph topology into the kernel?

- Direct geometric approach: K_{i,j} should be "large" when x_i and x_j are "close" to each other on the graph?
- Functional approach: $|| f ||_{\mathcal{K}}$ should be "small" when *f* is "smooth" on the graph?
- Link discrete/continuous: is there an equivalent to the continuous Gaussien kernel on the graph (e.g., limit by fine discretization)?

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Graph distance and p.d. kernels

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Hilbert distance

Any p.d. kernels is an inner product in a Hilbert space

$$\mathcal{K}\left(\mathbf{X},\mathbf{X}'
ight)=\left\langle \Phi\left(\mathbf{X}
ight),\Phi\left(\mathbf{X}'
ight)
ight
angle _{\mathcal{H}}\,.$$

It defines a Hilbert distance:

$$d_{\mathcal{K}}\left(\mathbf{x},\mathbf{x}'
ight)^{2}=\mathcal{K}\left(\mathbf{x},\mathbf{x}
ight)+\mathcal{K}\left(\mathbf{x}',\mathbf{x}'
ight)-2\mathcal{K}\left(\mathbf{x},\mathbf{x}'
ight)$$

• $-d_{K}^{2}$ is conditionally positive definite, i.e.:

$$\forall t > 0, \quad \exp\left(-td_{\mathcal{K}}\left(\mathbf{x}, \mathbf{x}'\right)^{2}\right) \text{ is p.d.}$$

Graph distance

Graph embedding in a Hilbert space

- Given a graph G = (V, E), the graph distance $d_G(x, x')$ between any two vertices is the length of the shortest path between x and x'.
- We say that the graph G = (V, E) can be embedded (exactly) in a Hilbert space if $-d_G$ is c.p.d., which implies in particular that $\exp(-td_G(x, x'))$ is p.d. for all t > 0.

Lemma

- In general graphs can not be embedded exactly in Hilbert spaces.
- In some cases exact embeddings exists, e.g.:
 - trees can be embedded exactly,
 - closed chains can be embedded exactly.

Graph distance

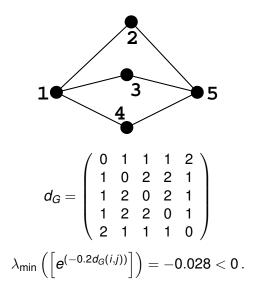
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Lemma

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Example: non-c.p.d. graph distance



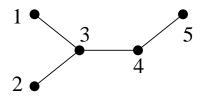
Proof

- Let G = (V, E) a tree
- Fix a root $x_0 \in V$
- Represent any vertex $x \in V$ by a vector $\Phi(x) \in \mathbb{R}^{|E|}$, where $\Phi(x)_i = 1$ is the *i*-th edge is in the (unique) path between *x* and x_0 , 0 otherwise.

Then:

$$d_G(x, x') = \| \Phi(x) - \Phi(x') \|^2$$
,

and therefore $-d_G$ is c.p.d., in particular $\exp(-td_G(x, x'))$ is p.d. for all t > 0.

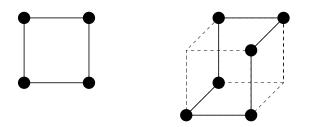


$$\begin{bmatrix} e^{-d_G(i,j)} \end{bmatrix} = \begin{pmatrix} 1 & 0.14 & 0.37 & 0.14 & 0.05 \\ 0.14 & 1 & 0.37 & 0.14 & 0.05 \\ 0.37 & 0.37 & 1 & 0.37 & 0.14 \\ 0.14 & 0.14 & 0.37 & 1 & 0.37 \\ 0.05 & 0.05 & 0.14 & 0.37 & 1 \end{pmatrix}$$

Graph distance on closed chains are c.p.d.

Proof: case |V| = 2p

- Let G = (V, E) a cycle with an even number of vertices |V| = 2p
- Fix a root $x_0 \in V$, number the 2*p* edges from x_0 to x_0 .
- Map the 2*p* edges in \mathbb{R}^p to $(e_1, \ldots, e_p, -e_1, \ldots, -e_p)$
- Map a vertex *v* to the sum of the edges in the shortest path between *x*₀ and *v*.



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Construction by regularization

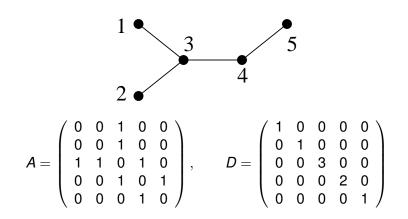
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Motivation

- How to make p.d. kernel on general graphs?
- Making a kernel is equivalent to defining a RKHS.
- There are intuitive notions of smoothness on a graph

Idea

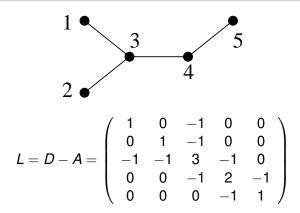
- Define a priori a smoothness functional on the functions $f : \mathcal{X} \to \mathbb{R}$.
- Show that it defines a RKHS and identify the corresponding kernel



Graph Laplacian

Definition

The Laplacian of the graph is the matrix L = D - A.



Properties of the Laplacian

Lemma

Let L = D - A be the Laplacian of a connected graph:

• For any $f: \mathcal{X} \to \mathbb{R}$,

$$\Omega(f) := \sum_{i \sim j} \left(f(\mathbf{x}_i) - f(\mathbf{x}_j) \right)^2 = f^\top L f$$

- L is a symmetric positive semi-definite matrix
- 0 is an eigenvalue with multiplicity 1 associated to the constant eigenvector 1 = (1,...,1)
- The image of L is

$$\mathit{Im}(L) = \left\{ f \in \mathbb{R}^m : \sum_{i=1}^m f_i = 0 \right\}$$

Proof: link between $\Omega(f)$ and L

$$\begin{aligned} \Omega(f) &= \sum_{i \sim j} \left(f(\mathbf{x}_i) - f(\mathbf{x}_j) \right)^2 \\ &= \sum_{i \sim j} \left(f(\mathbf{x}_i)^2 + f(\mathbf{x}_j)^2 - 2f(\mathbf{x}_i) f(\mathbf{x}_j) \right) \\ &= \sum_{i=1}^m D_{i,i} f(\mathbf{x}_i)^2 - 2 \sum_{i \sim j} f(\mathbf{x}_i) f(\mathbf{x}_j) \\ &= f^\top D f - f^\top A f \\ &= f^\top L f \end{aligned}$$

Proof: eigenstructure of L

- *L* is symmetric because *A* and *D* are symmetric.
- For any f ∈ ℝ^m, f^TLf = Ω(f) ≥ 0, therefore the (real-valued) eigenvalues of L are ≥ 0 : L is therefore positive semi-definite.
- *f* is an eigenvector associated to eigenvalue 0 iff $f^{\top}Lf = 0$ iff $\sum_{i \sim j} (f(\mathbf{x}_i) - f(\mathbf{x}_j))^2 = 0$, iff $f(\mathbf{x}_i) = f(\mathbf{x}_j)$ when $i \sim j$, iff *f* is constant (because the graph is connected).
- *L* being symmetric, Im(L) is the orthogonal supplement of Ker(L), that is, the set of functions orthogonal to **1**.

Theorem

The set $\mathcal{H} = \{f \in \mathbb{R}^m : \sum_{i=1}^m f_i = 0\}$ endowed with the norm:

$$\Omega\left(f\right) = \sum_{i \sim j} \left(f\left(\mathbf{x}_{i}\right) - f\left(\mathbf{x}_{j}\right)\right)^{2}$$

is a RKHS whose reproducing kernel is L*, the pseudo-inverse of the graph Laplacian.

• Resticted to \mathcal{H} , the symmetric bilinear form:

$$\langle f, g \rangle = f^\top L g$$

is positive definite (because *L* is positive semi-definite, and $\mathcal{H} = Im(L)$). It is therefore a scalar product, making of \mathcal{H} a Hilbert space (in fact Euclidean).

• The norm in this Hilbert space \mathcal{H} is:

$$|| f ||^2 = \langle f, f \rangle = f^\top L f = \Omega(f) .$$

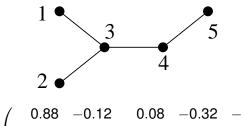
To check that \mathcal{H} is a RKHS with reproducing kernel $K = L^*$, it suffices to show that:

$$\begin{cases} \forall \mathbf{x} \in \mathcal{X}, & \mathbf{K}_{\mathbf{x}} \in \mathcal{H}, \\ \forall (\mathbf{x}, f) \in \mathcal{X} \times \mathcal{H}, & \langle f, \mathbf{K}_{\mathbf{x}} \rangle = f(\mathbf{x}) \end{cases}.$$

- Ker(K) = Ker(L*) = Ker(L), implying K1 = 0. Therefore, each row/column of K is in H.
- For any $f \in \mathcal{H}$, if we note $g_i = \langle K(i, \cdot), f \rangle$ we get:

$$g = KLf = L^*Lf = \Pi_{\mathcal{H}}(f) = f$$
.

As a conclusion $K = L^*$ is the reproducing kernel of \mathcal{H} . \Box



	/ 0.88	-0.12	0.08	-0.32	-0.52 \	
	-0.12	0.88	0.08	-0.32	-0.52	
<i>L</i> * =	0.08	0.08	0.28	-0.12	-0.32	
	-0.32	-0.32	-0.12	0.48	0.28	
	\ −0.52	-0.52	-0.32	0.28	$\begin{array}{c} -0.52 \\ -0.52 \\ -0.32 \\ 0.28 \\ 1.08 \end{array}$	

Statistical learning with positive definite kernels

Kernels on graphs

- Motivation
- Graph distance and p.d. kernels
- Construction by regularization
- The diffusion kernel
- Harmonic analysis on graphs
- Applications

Lemma

For any $\mathbf{x}_0 \in \mathbb{R}^d$, the function:

$$K_{\mathbf{x}_{0}}(\mathbf{x},t) = K_{t}(\mathbf{x}_{0},\mathbf{x}) = \frac{1}{(4\pi t)^{\frac{d}{2}}} \exp\left(-\frac{\|\mathbf{x}-\mathbf{x}_{0}\|^{2}}{4t}\right)$$

is solution of the diffusion equation:

$$\frac{\partial}{\partial t} \mathcal{K}_{\mathbf{x}_{0}}\left(\mathbf{x},t\right) = \Delta \mathcal{K}_{\mathbf{x}_{0}}\left(\mathbf{x},t\right).$$

with initial condition $K_{\mathbf{x}_0}(\mathbf{x}, \mathbf{0}) = \delta_{\mathbf{x}_0}(\mathbf{x})$.

Discrete diffusion equation

• For finite-dimensional $f_t \in \mathbb{R}^m$, the diffusion equation becomes:

$$\frac{\partial}{\partial t}f_t = -Lf_t$$

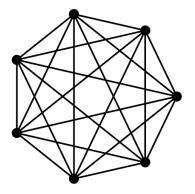
which admits the following solution:

$$f_t = f_0 e^{-tL}$$

$$K = e^{-tL}$$

which is indeed symmetric positive semi-definite. We call it the diffusion kernel or heat kernel.

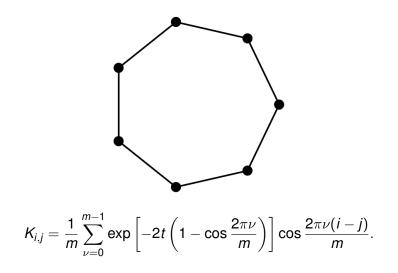
Example: complete graph

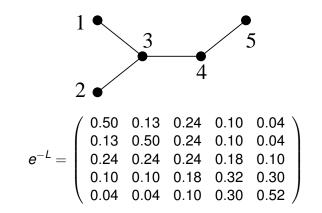


$$K_{i,j} = \begin{cases} \frac{1 + (m-1)e^{-tm}}{m} & \text{ for } i = j, \\ \frac{1 - e^{-tm}}{m} & \text{ for } i \neq j. \end{cases}$$

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Example: closed chain





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Applications

• Let $0 = \lambda_1 < \lambda_2 \leq \ldots \leq \lambda_m$ be the eigenvalues of the Laplacian:

$$L = \sum_{i=1}^{m} \lambda_i u_i u_i^{\top} \quad (\lambda_i \ge \mathbf{0})$$

 The diffusion kernel K_t is an invertible matrix because its eigenvalues are strictly positive:

$$K_t = \sum_{i=1}^m e^{-t\lambda_i} u_i u_i^{\top}$$

• For any function $f \in \mathbb{R}^m$, let:

$$\hat{f}_i = u_i^{\top} f$$

be the Fourier coefficients of f (projection of f onto the eigenbasis of K).

• The RKHS norm of *f* is then:

$$|| f ||_{K_t}^2 = f^\top K^{-1} f = \sum_{i=1}^m e^{t\lambda_i} \hat{t}_i^2.$$

This observation suggests to define a whole family of kernels:

$$K_r = \sum_{i=1}^m r(\lambda_i) u_i u_i^{\top}$$

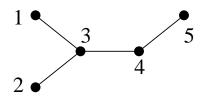
associated with the following RKHS norms:

$$\| f \|_{K_r}^2 = \sum_{i=1}^m \frac{\hat{f}_i^2}{r(\lambda_i)}$$

where $r : \mathbb{R}^+ \to \mathbb{R}^+_*$ is a non-increasing function.

Example : regularized Laplacian

$$r(\lambda) = \frac{1}{\lambda + \epsilon}, \qquad \epsilon > 0$$
$$K = \sum_{i=1}^{m} \frac{1}{\lambda_i + \epsilon} u_i u_i^{\top} = (L + \epsilon I)^{-1}$$
$$\| f \|_{K}^{2} = f^{\top} K^{-1} f = \sum_{i \sim j} \left(f(\mathbf{x}_i) - f(\mathbf{x}_j) \right)^{2} + \epsilon \sum_{i=1}^{m} f(\mathbf{x}_i)^{2}.$$



	/ 0.60	0.10	0.19	0.08	0.04 \
	0.10	0.60	0.19	0.08	0.04
$(L + I)^{-1} =$	0.19	0.19	0.38	0.15	0.08
	0.08	0.08	0.15	0.46	0.23
$(L + I)^{-1} =$	0.04	0.04	0.08	0.23	0.62 /

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Applications 1: graph partitioning

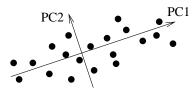
• A classical relaxation of graph partitioning is:

$$\min_{f \in \mathbb{R}^{\mathcal{X}}} \sum_{i \sim j} \left(f_i - f_j \right)^2 \quad \text{s.t.} \sum_i f_i^2 = 1$$

This can be rewritten

$$\max_{f} \sum_{i} f_{i}^{2} \text{ s.t. } \| f \|_{\mathcal{H}} \leq 1$$

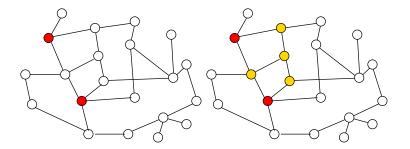
This is principal component analysis in the RKHS ("kernel PCA")



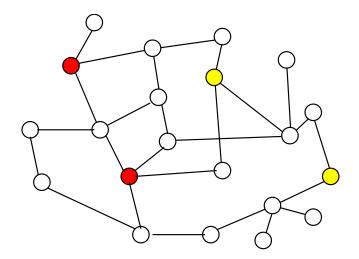
Applications 2: search on a graph

- Let x₁,..., x_q a set of q nodes (the query). How to find "similar" nodes (and rank them)?
- One solution:

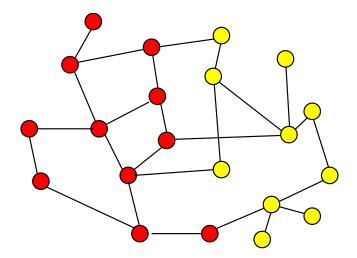
 $\min_{f} \|f\|_{\mathcal{H}} \quad \text{s.t.} \quad f(x_i) \geq 1 \text{ for } i = 1, \dots, q.$



Application 3: Semi-supervised learning



Application 3: Semi-supervised learning



Application 4: Tumor classification from microarray data

Data available

- Gene expression measures for more than 10k genes
- Measured on less than 100 samples of two (or more) different classes (e.g., different tumors)

Goal

- Design a classifier to automatically assign a class to future samples from their expression profile
- Interpret biologically the differences between the classes

Application 4: Tumor classification from microarray data

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Linear classifiers

The approach

- Each sample is represented by a vector x = (x₁,..., x_p) where p > 10⁵ is the number of probes
- Classification: given the set of labeled sample, learn a linear decision function:

$$f(x) = \sum_{i=1}^{p} \beta_i x_i + \beta_0 ,$$

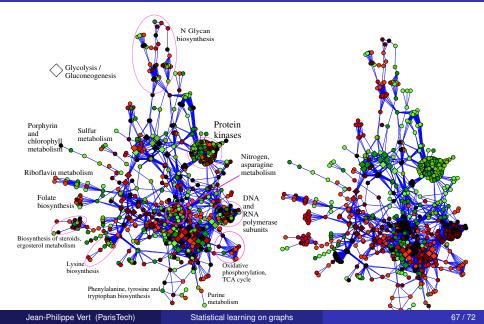
 Interpretation: the weight β_i quantifies the influence of gene *i* for the classification

Pitfalls

 No robust estimation procedure exist for 100 samples in 10⁵ dimensions!

- We know the functions of many genes, and how they interact together.
- This can be represented as a graph of genes, where connected genes perform some action together
- Prior knowledge: constraint the weights of genes that work together to be similar
- Mathematically: constrain the norm of the weight vector in the RKHS of the diffusion kernel.

Comparison



Conclusion

Conclusion

What we saw

- Extension of machine learning algorithms to graph data through the definition of positive definite kernels for and on graphs
- A variety of solutions have been proposed, borrowing ideas from graph algorithms and spectral graph theory.
- Increasingly used in real-world applications.

Unanswered question

- Theoretical foundations to guide the choice of kernel?
- How to design / choose / learn a kernel for a given application in practice?
- How to improve scalability of kernel methods + graph kernels to large datasets?

Further reading

Kernels and RKHS: general

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